



Dynamic Graphs

SSMC '23 | University of Kentucky

May 20, 2023 @ 3:15 PM

Dev Dabke

Overview

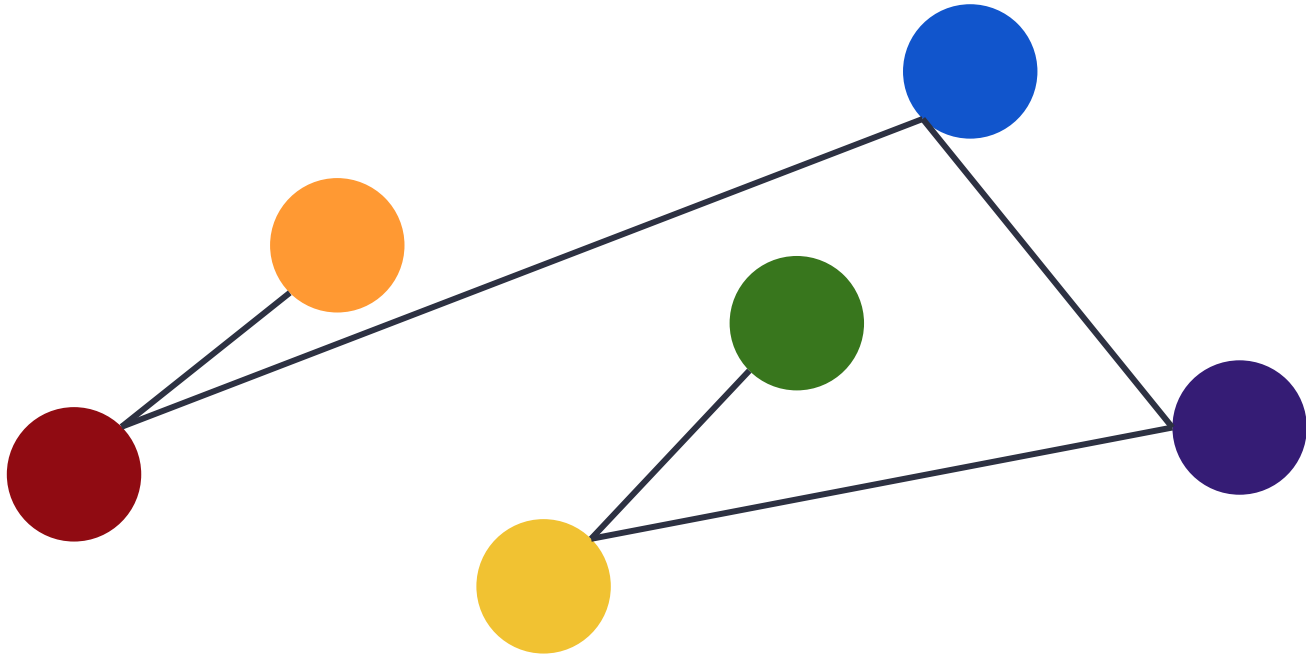
1. Brief mathematical introduction
2. Some observations and conjectures
3. An ML thing (if we have time)



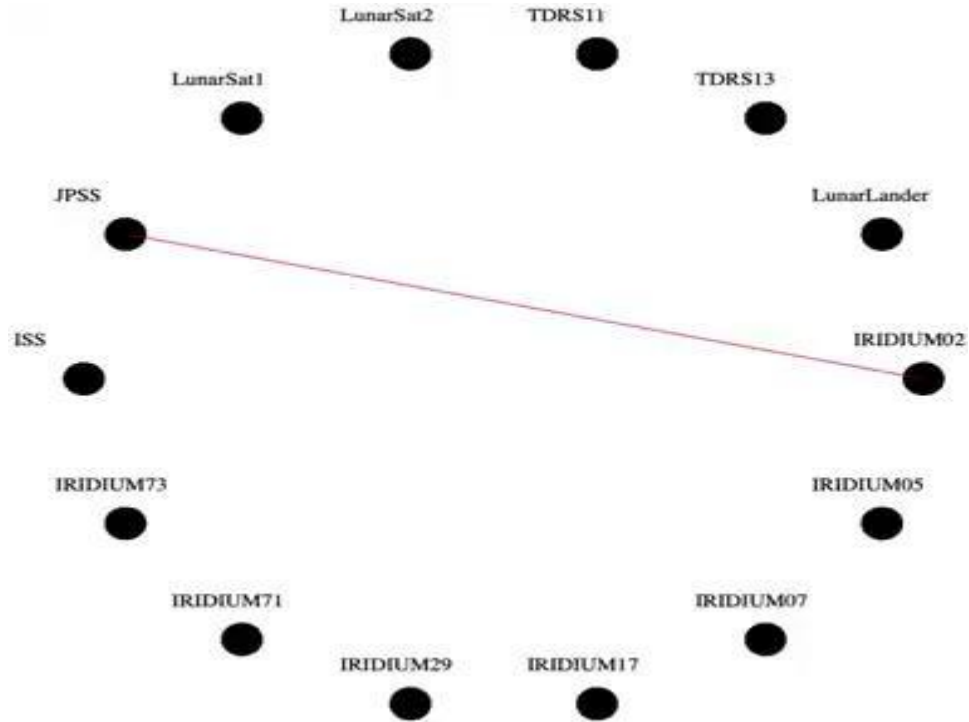


Math Intro

1	2
3	4



A simple graph



A dynamic graph

Definition: Dynamic Graph

Dynamic graph $\mathcal{G} = (G_t)_{t \in \mathbb{T}}$ where

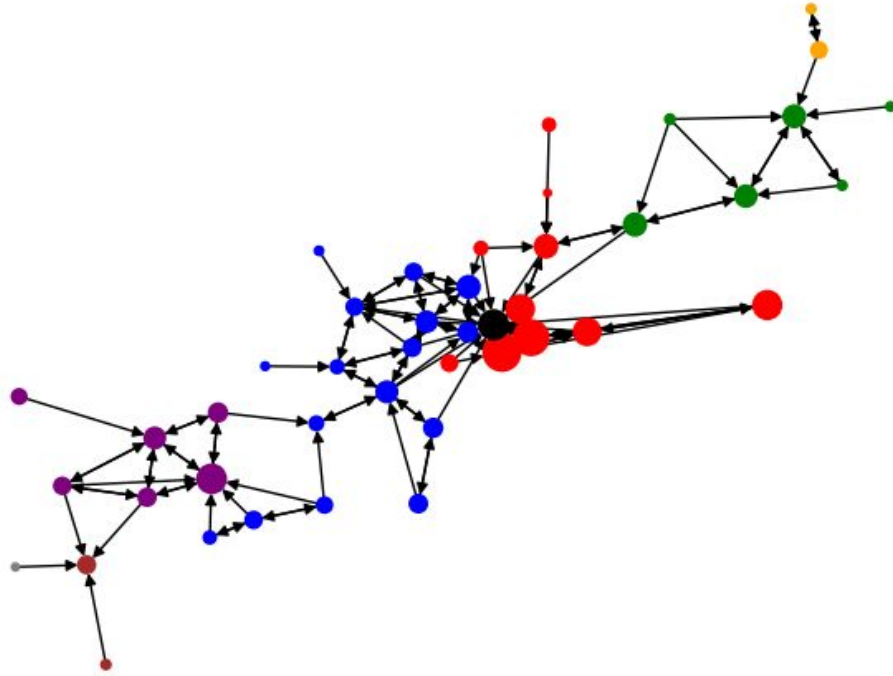
1. totally ordered indexing set \mathbb{T}
2. fixed finite vertex set V
3. edge set sequence $(E_t \subseteq V \times V)_{t \in \mathbb{T}}$
4. $G_t = (V, E_t)$



Dynamic Graphs

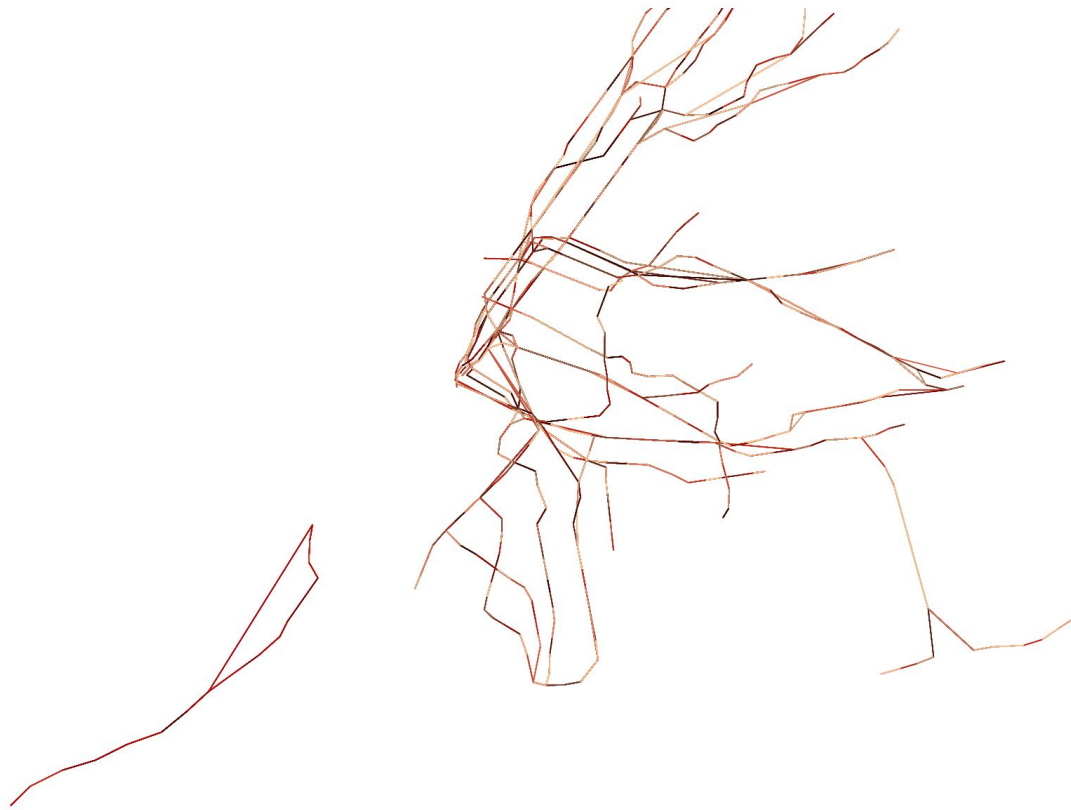
are **Everywhere**

- Commute networks
 - Animal interaction networks
 - Opinion dynamics
 - Cell-cell signaling
 - Social networks
 - Satellite communication networks
 - Basketball, sports
 - Bird flocking
-



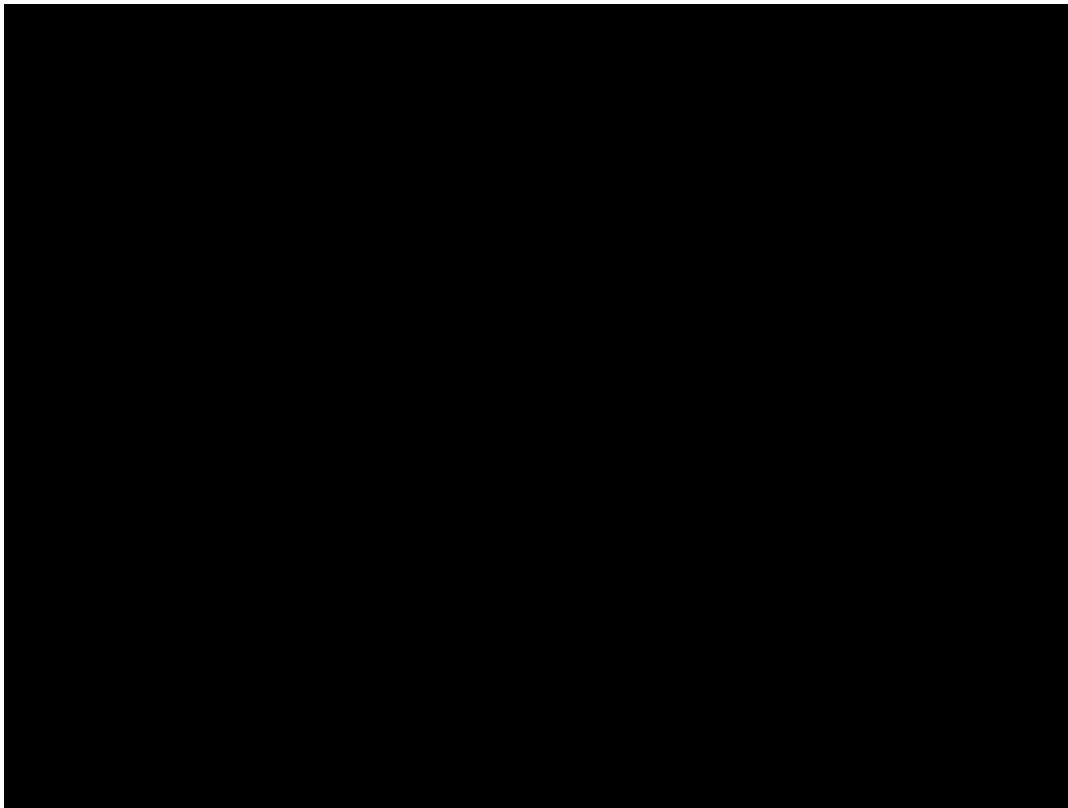
NYC Metro Area Commute Network

Dabke, Karntikoon, Aluru, Singh, Chazelle. *Network-augmented compartmental models to track asymp. disease spread.* (pre-print)



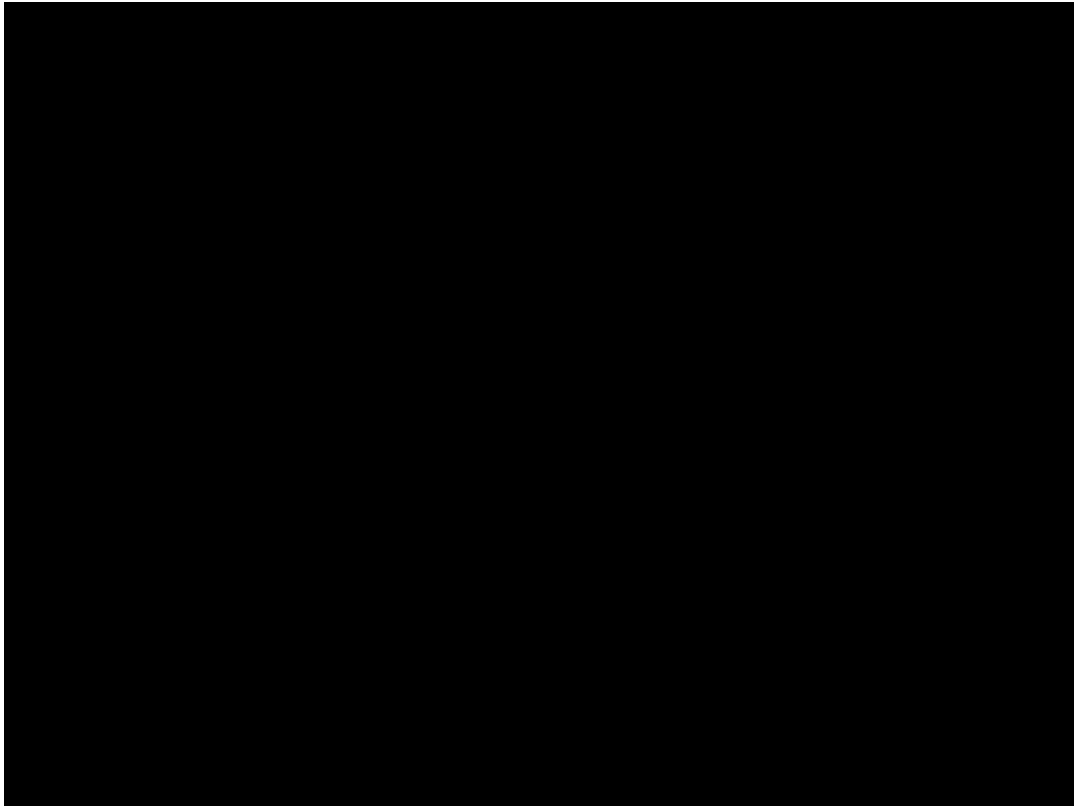
Transit Networks (GTFS)

Dabke, Green. *Analyzing transit networks with ideal routing machines.* (pre-print)

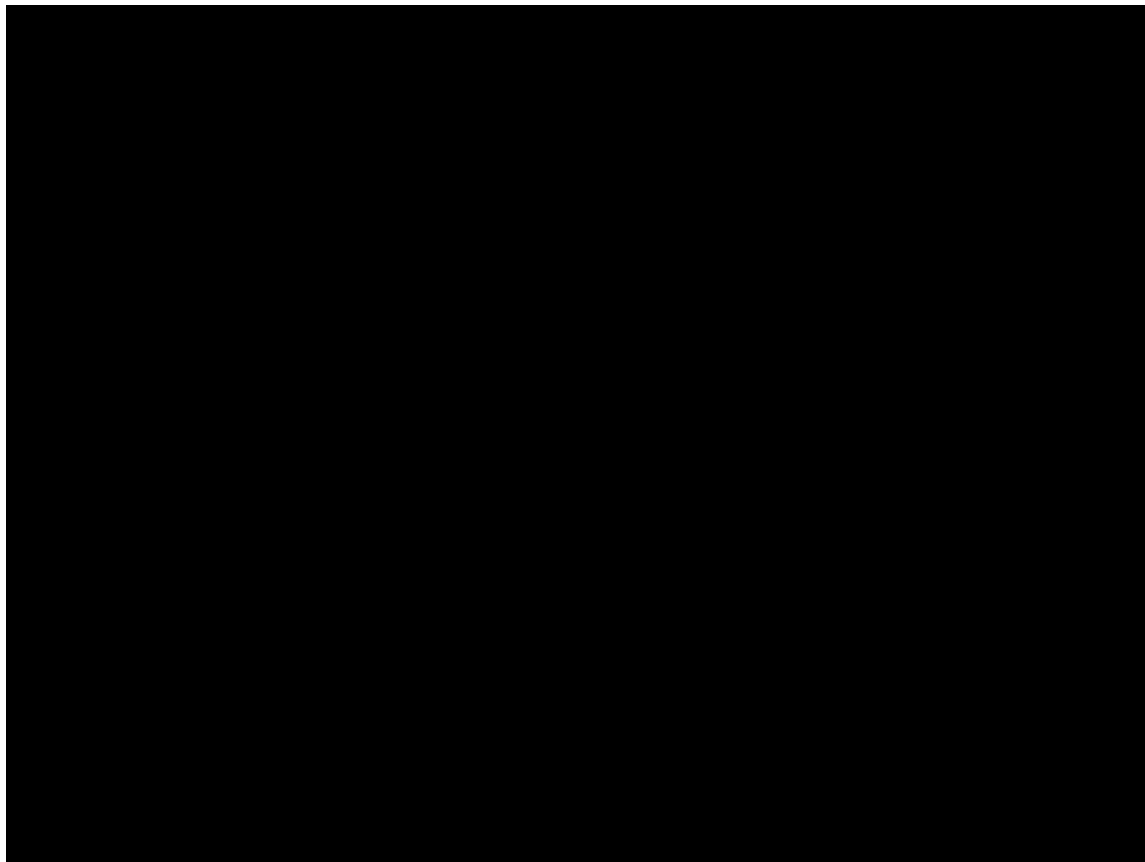


Animal herding networks

Dorabiala, Dabke, et al. *Spatiotemporal k-means*. (pre-print)



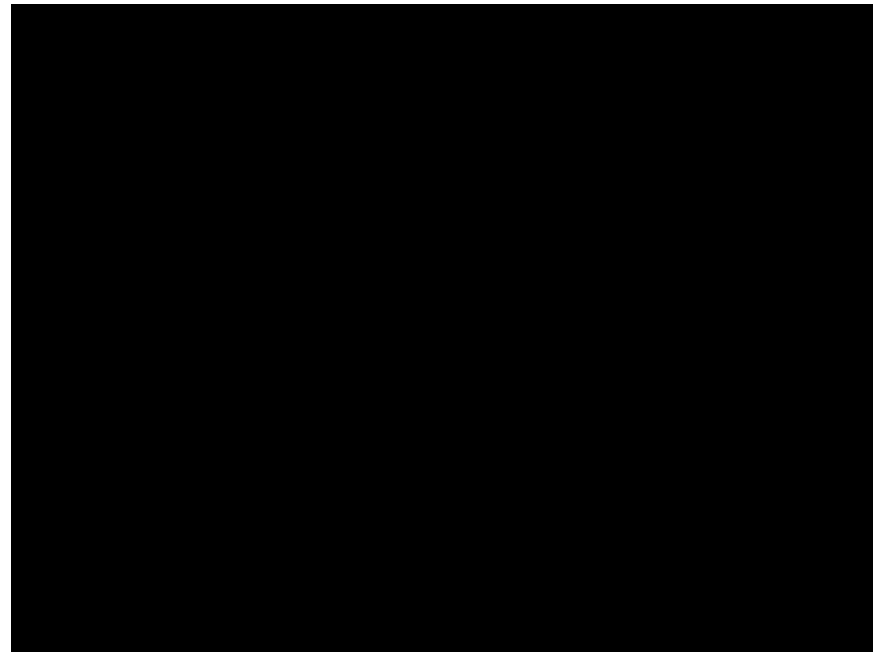
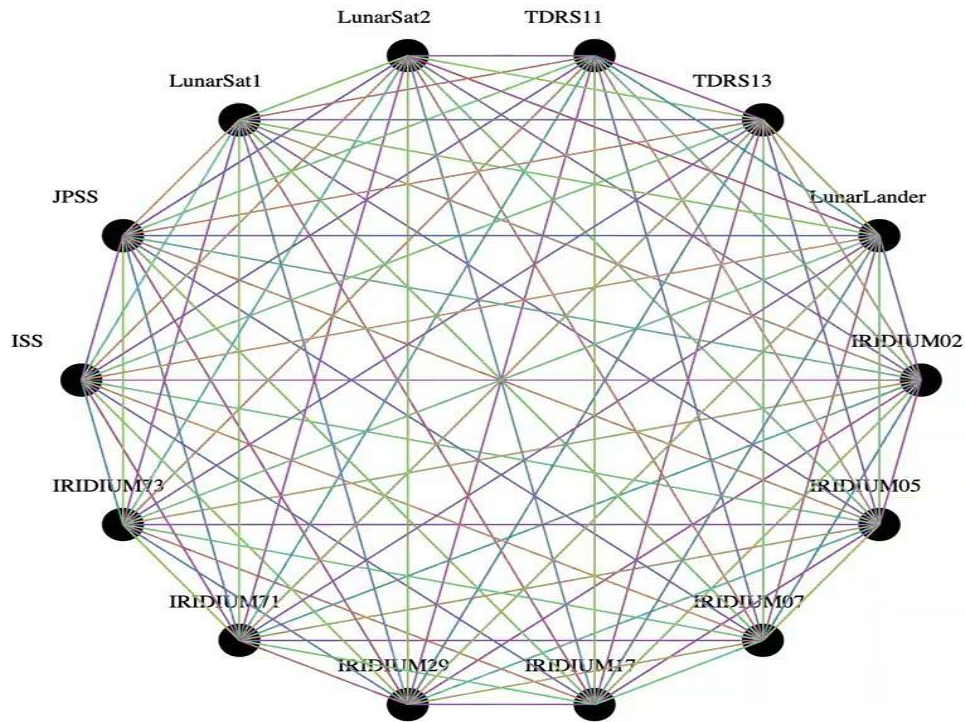
Embryos: spatial and chemical connectivity



Basketball

Dabke, Chazelle. *Extracting semantic information from dynamic graphs of geometric data.*

Dabke, Taylor. *Play classification in basketball networks.* (internal publication; pre-print)



NASA: Satellites

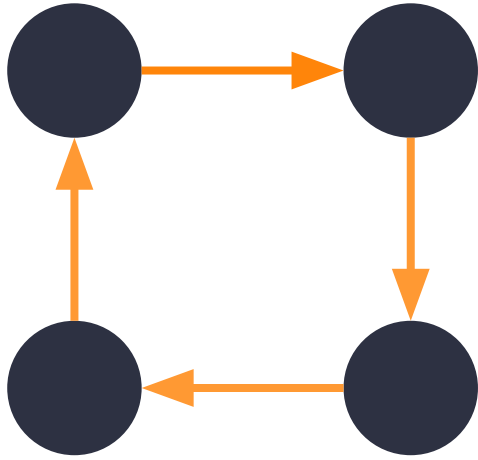
Cleveland, Dabke, et al. *Introducing tropical geometric approaches to delay tolerant networking optimization.*

Hylton, Dabke, et al. *A survey of mathematical structures for lunar networks.*

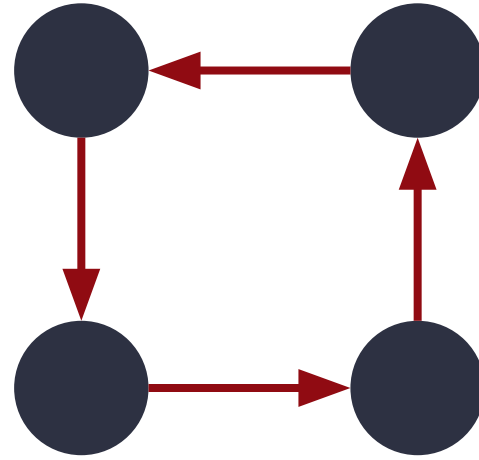
Some Problems

Problem

Local \neq Global

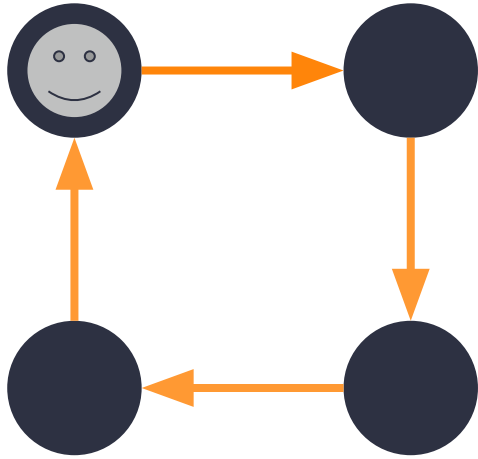


$t = 1, 3, 5, \dots$

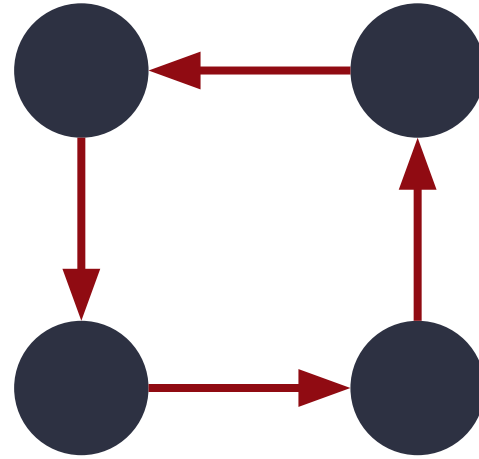


$t = 2, 4, 6, \dots$

The alternating cycle: a discrete-time sequence

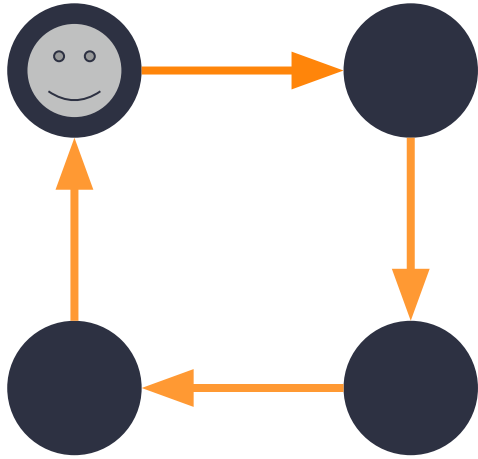


$t = 1, 3, 5, \dots$

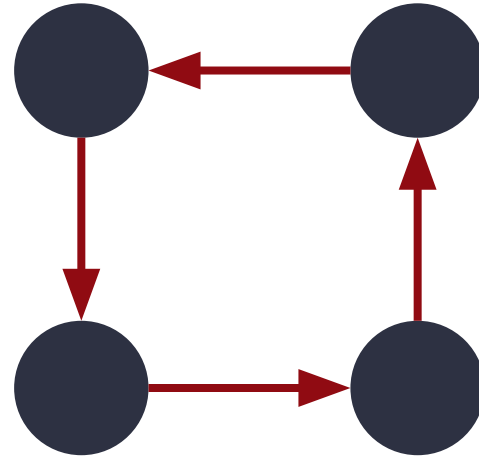


$t = 2, 4, 6, \dots$

Dynamical system: move one edge at each time step

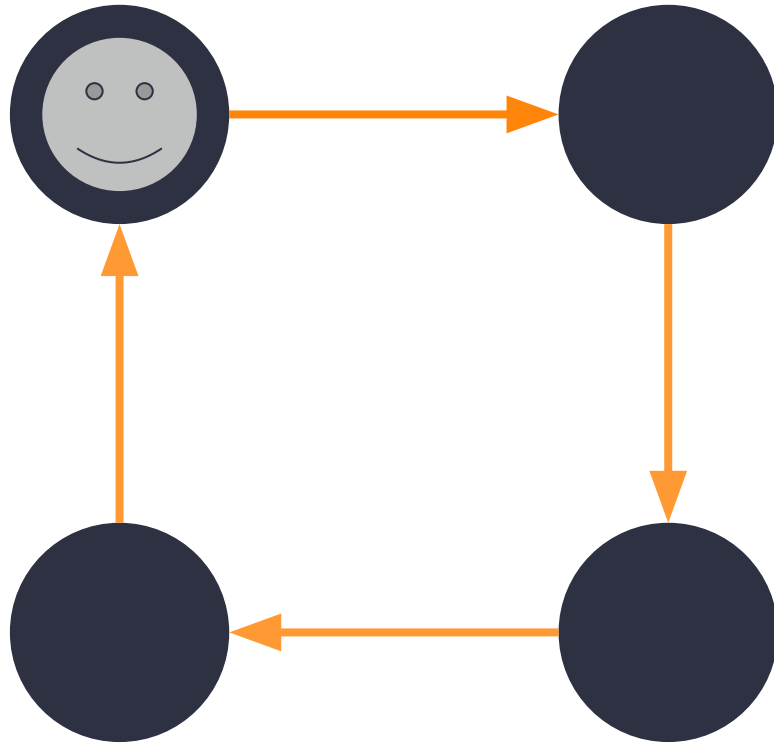


$t = 1, 3, 5, \dots$

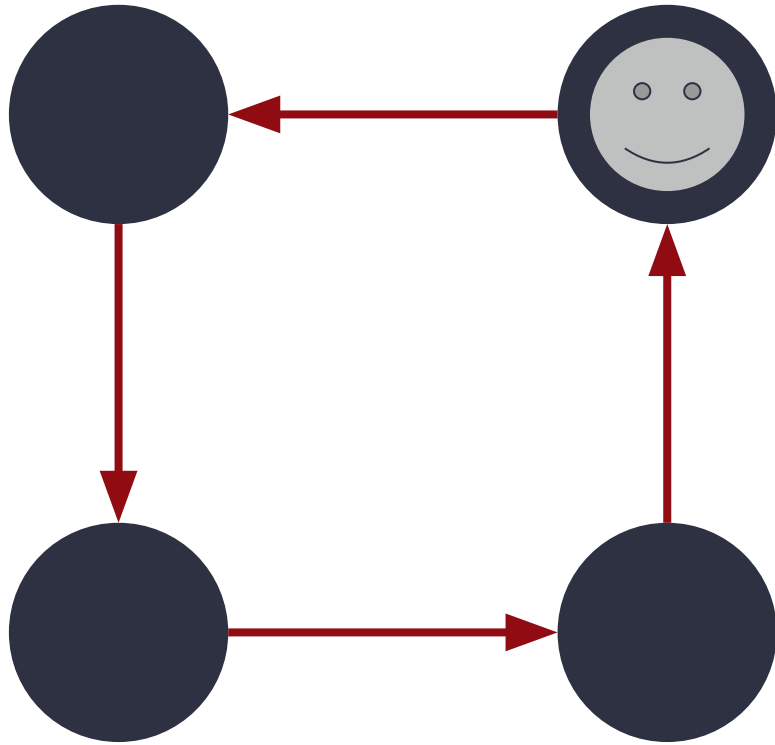


$t = 2, 4, 6, \dots$

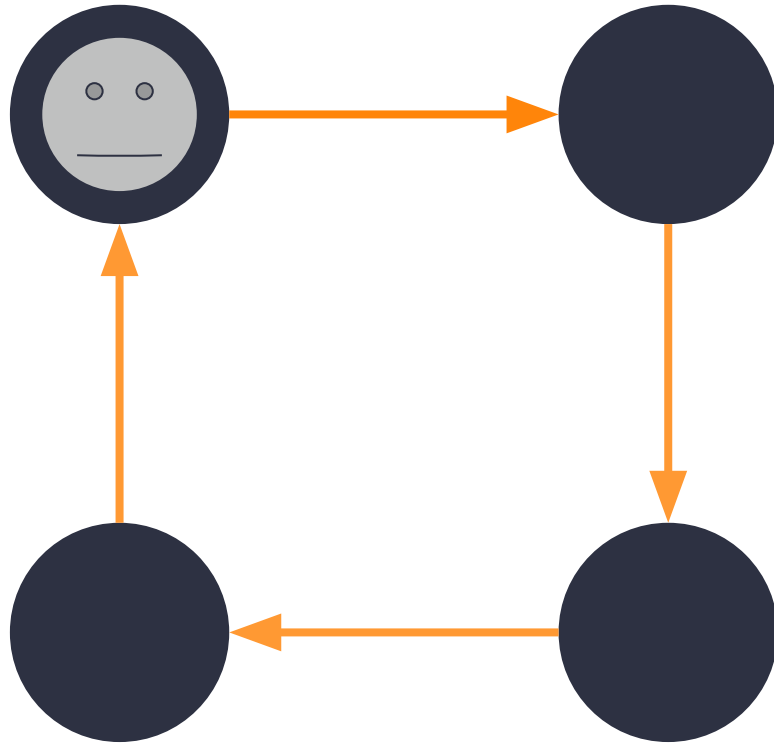
Fact: max diameter is number of vertices (if connected)



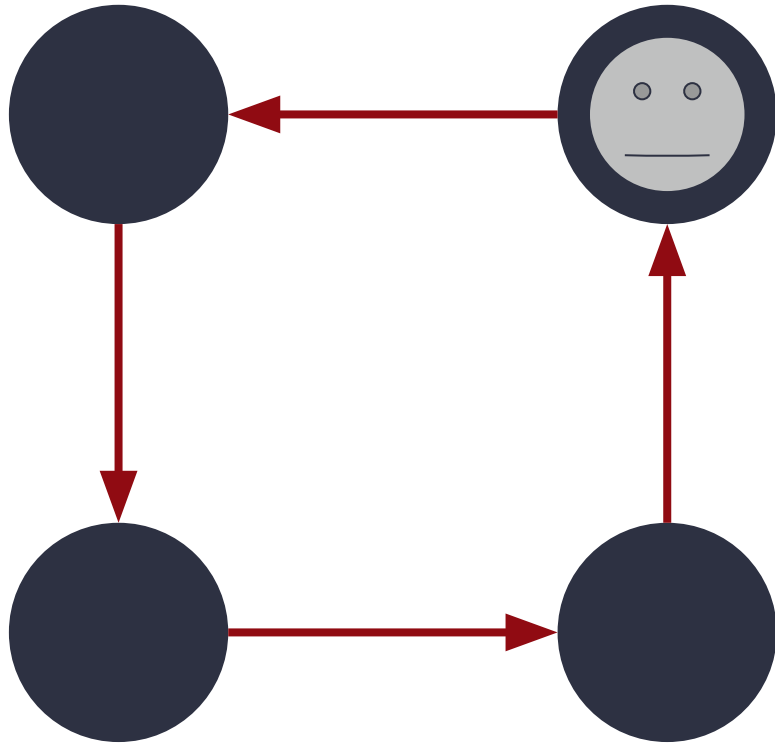
t = 1



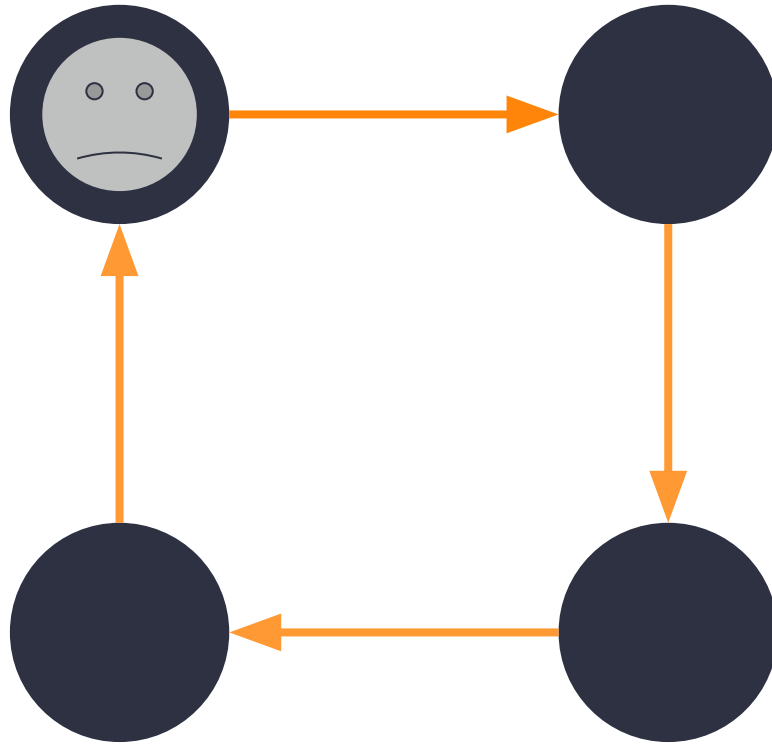
t=2



t = 3



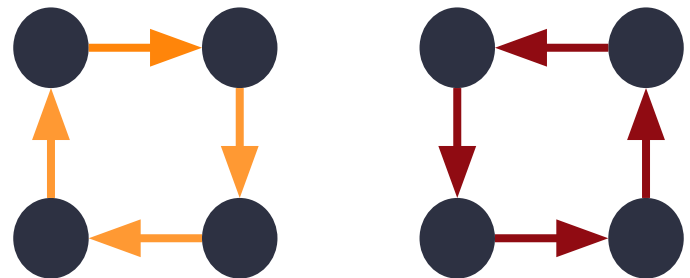
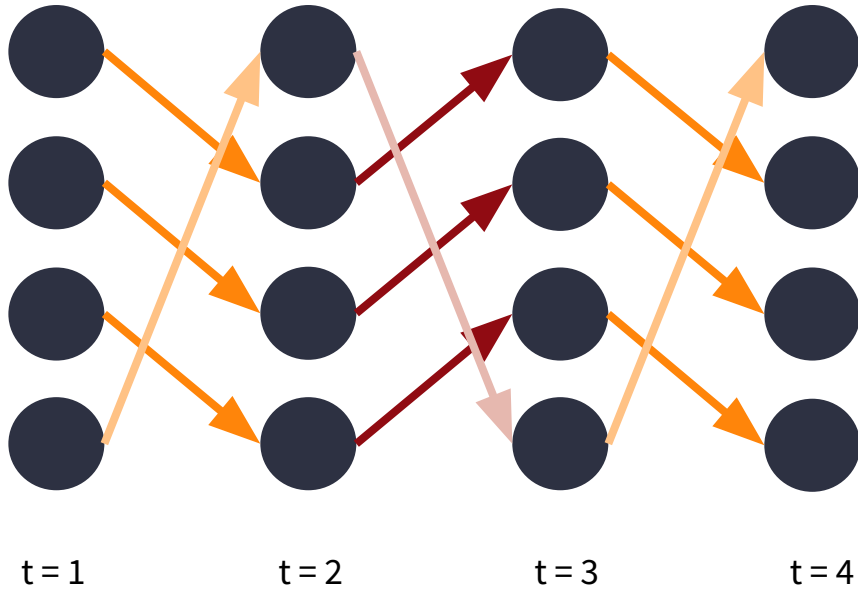
t = 4



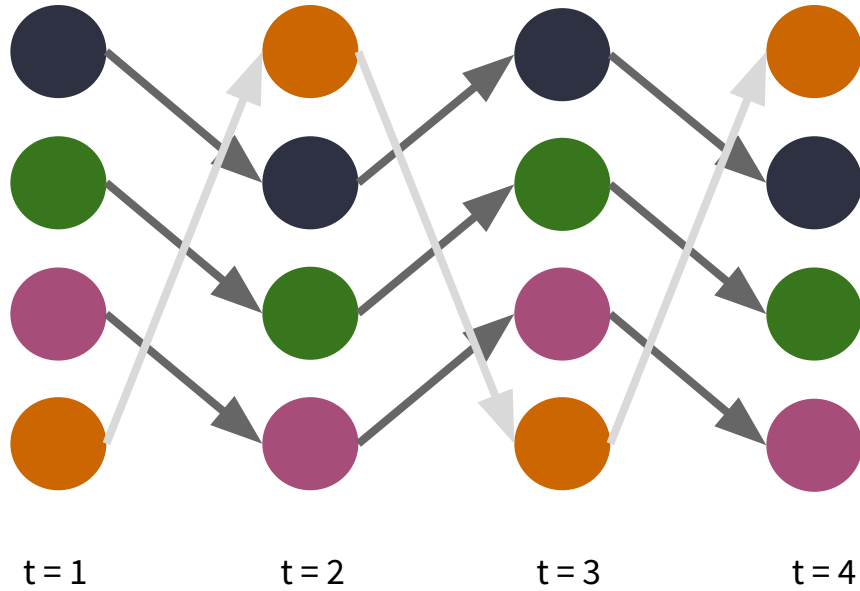
t = 5



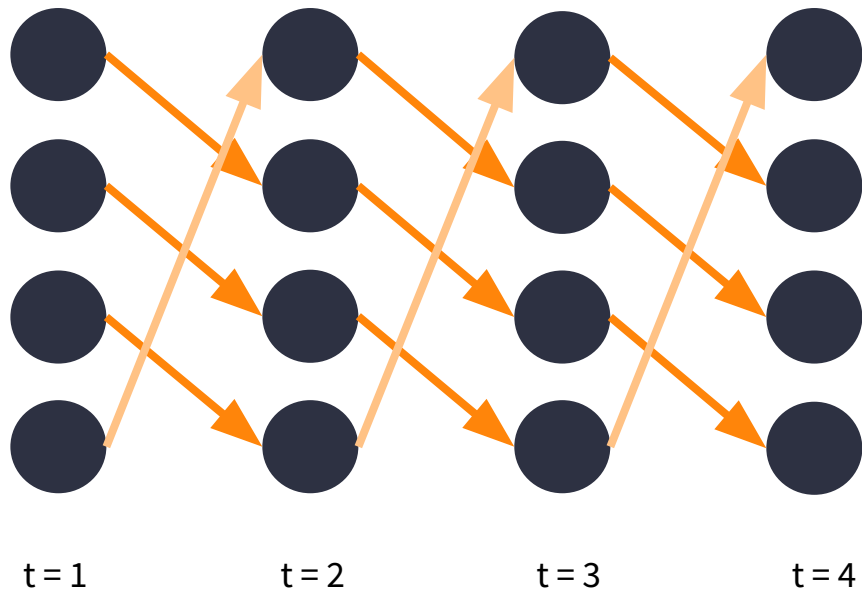
Dynamically disconnected



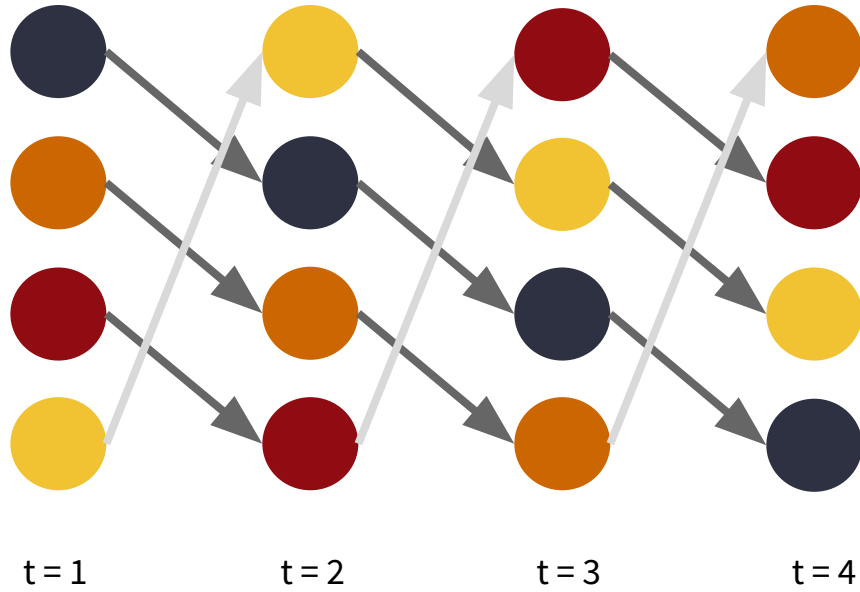
Idea: time-expanded graph



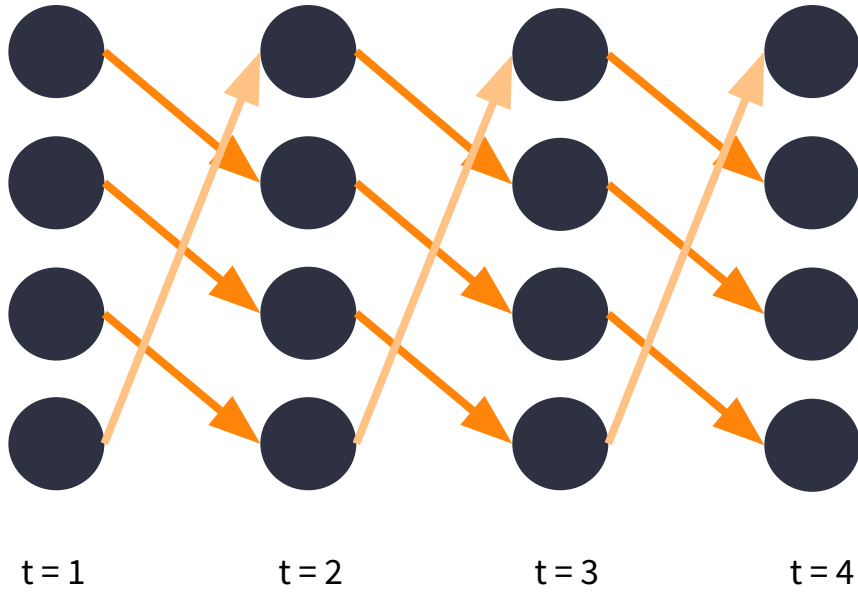
Observation: disconnected \Rightarrow dynamically disconnected?



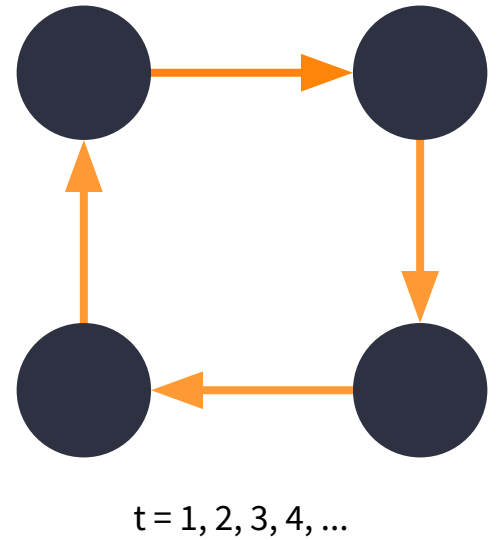
This one?

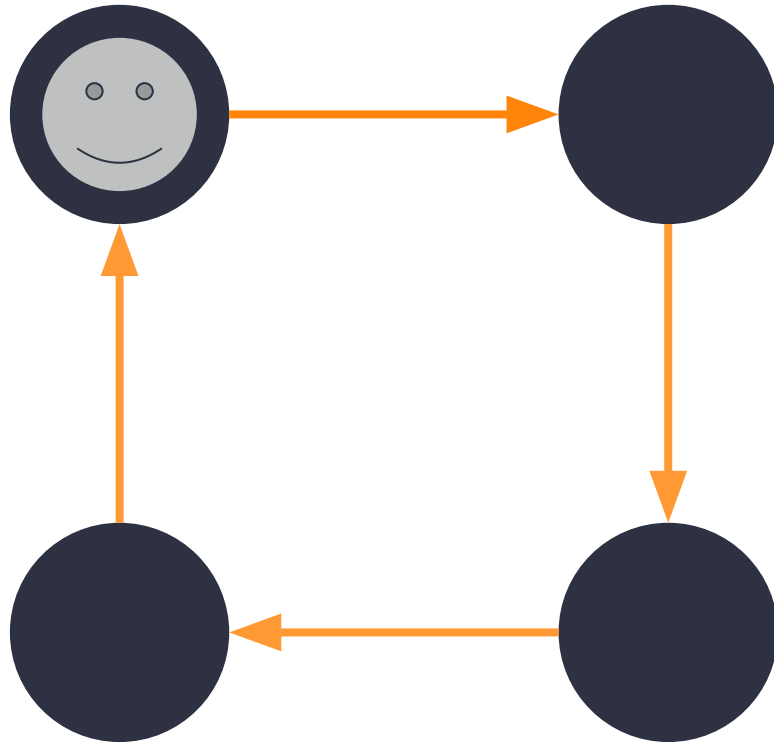


Disconnected again

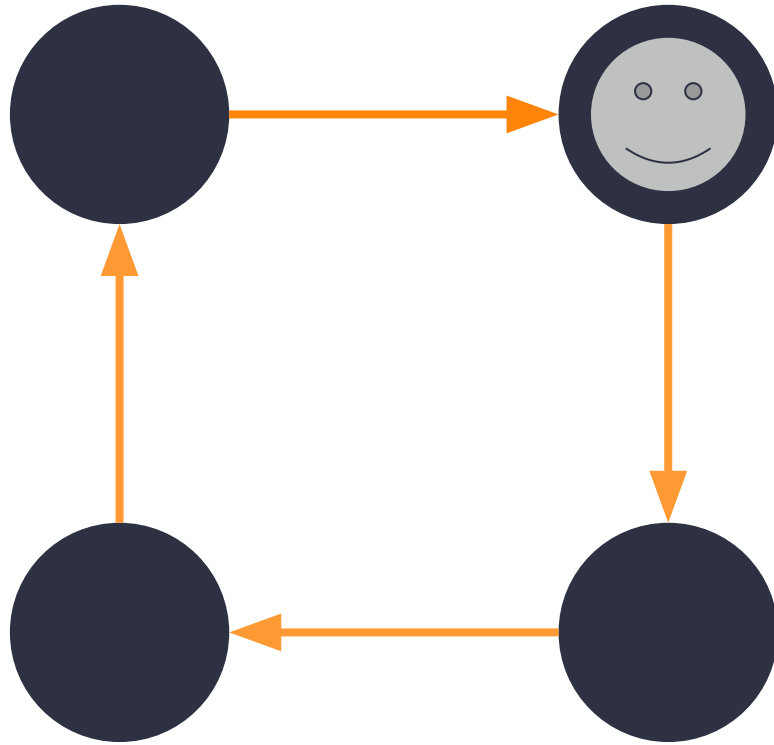


Time-expanded fixed cycle

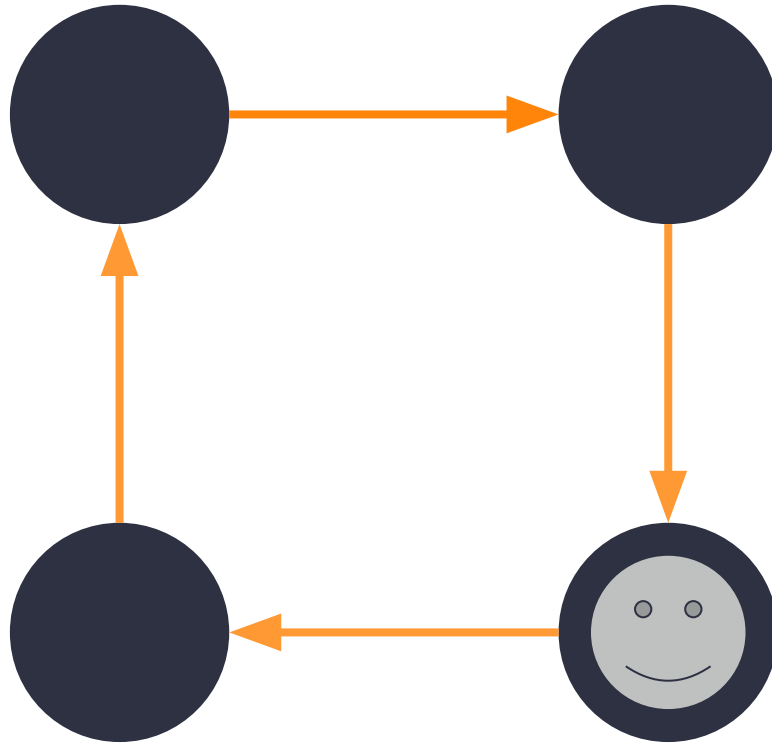




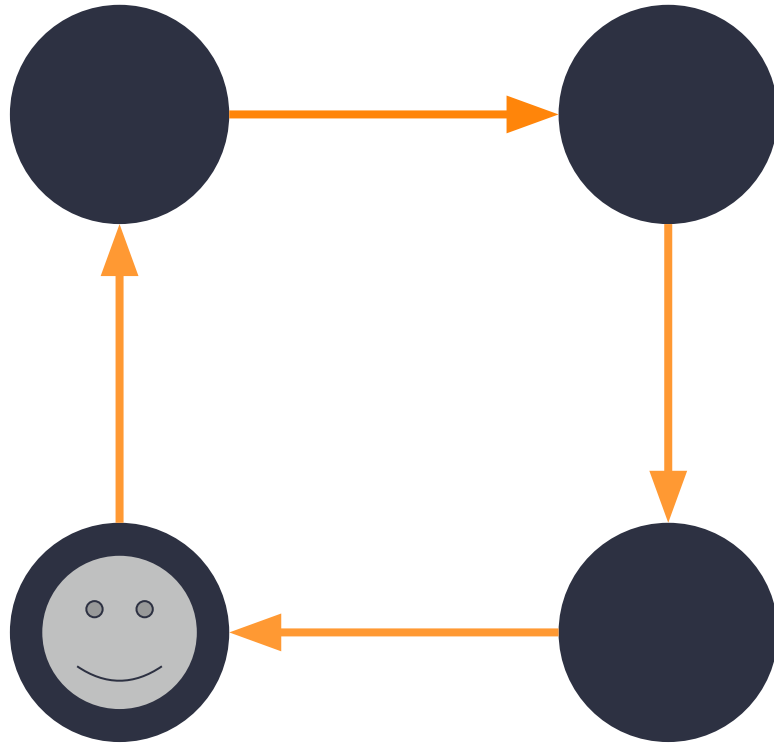
t = 1



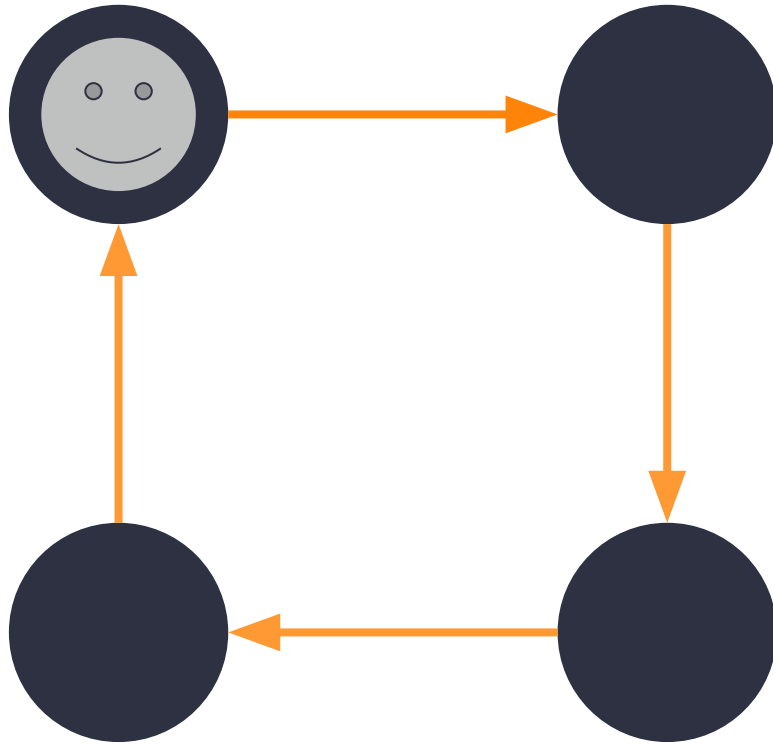
t=2



t = 3



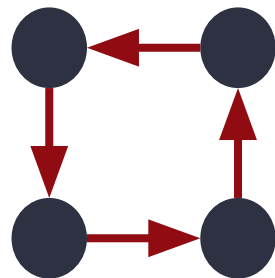
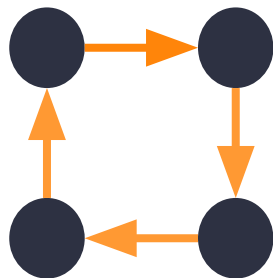
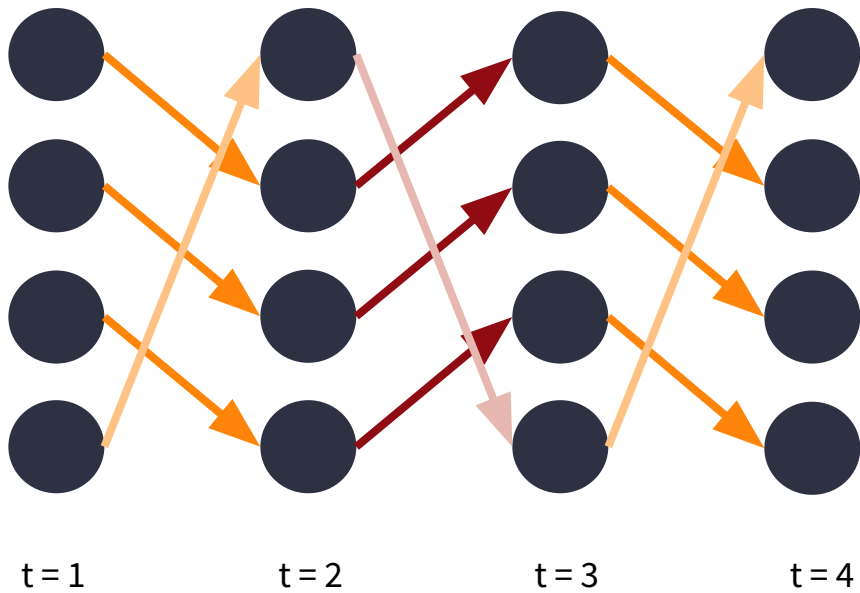
t = 4



t = 5

Problem

$$\mathbf{v} = \mathbf{n} * \mathbf{t}$$



too many nodes

Many Problems Don't “Just Work”

- Can we relate static and dynamic properties?
- How do we recover classical algorithms?
- Is there an efficient way to do all this?



 Theory 

Two Orthogonal Dichotomies

Length

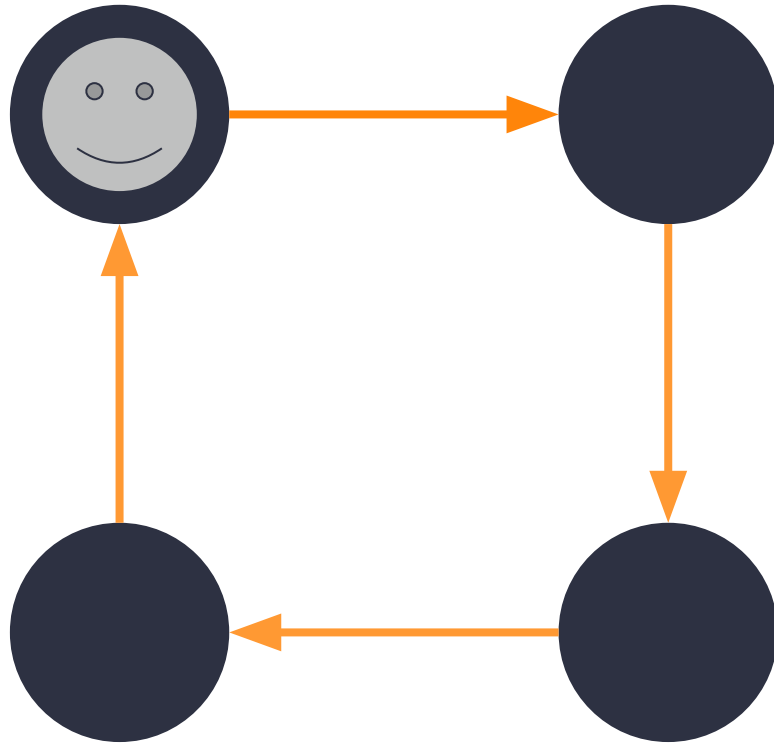
finite vs. infinite

Discretization

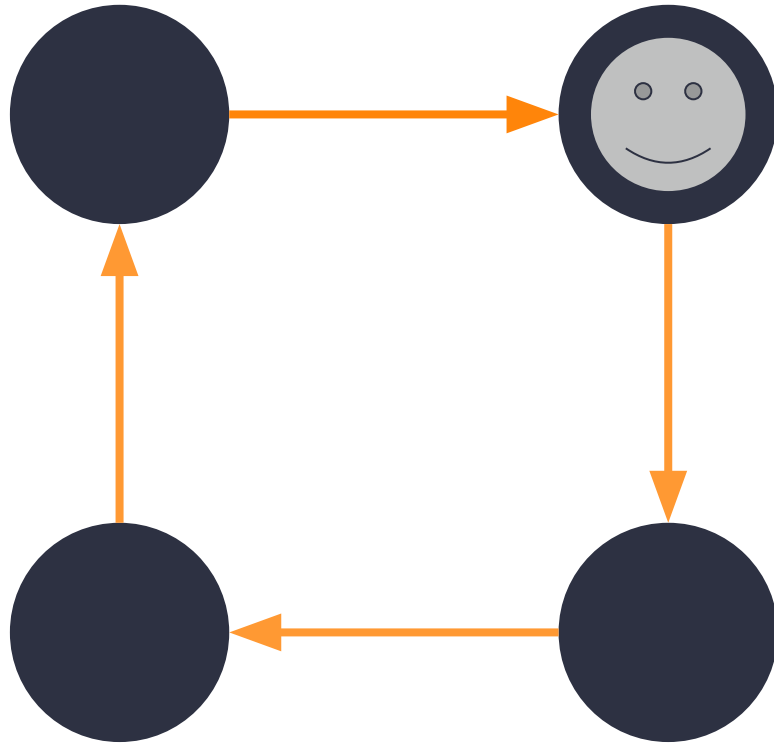
discrete-time vs. continuous-time

Dynamic Connectivity

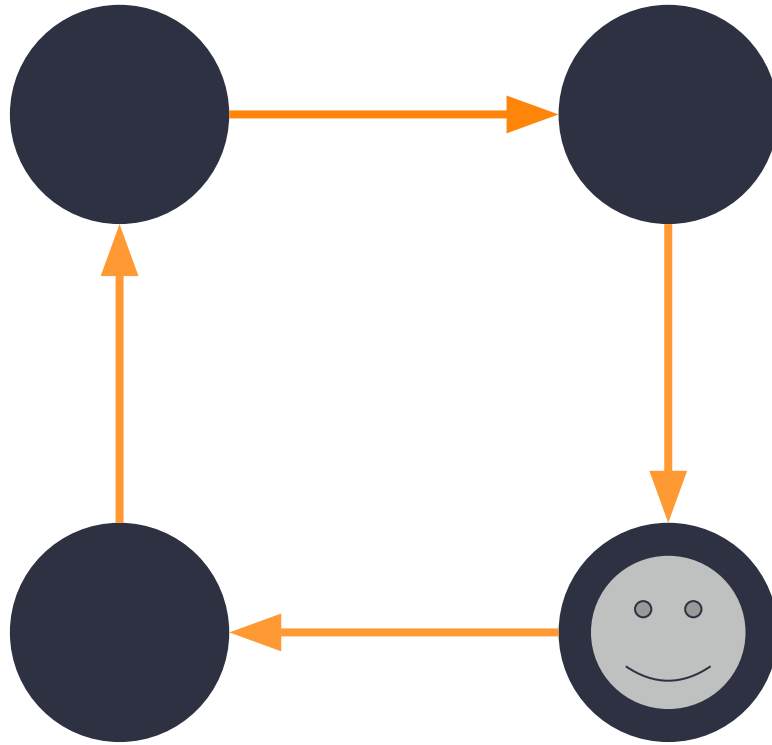
Journeys are
Dynamic Paths



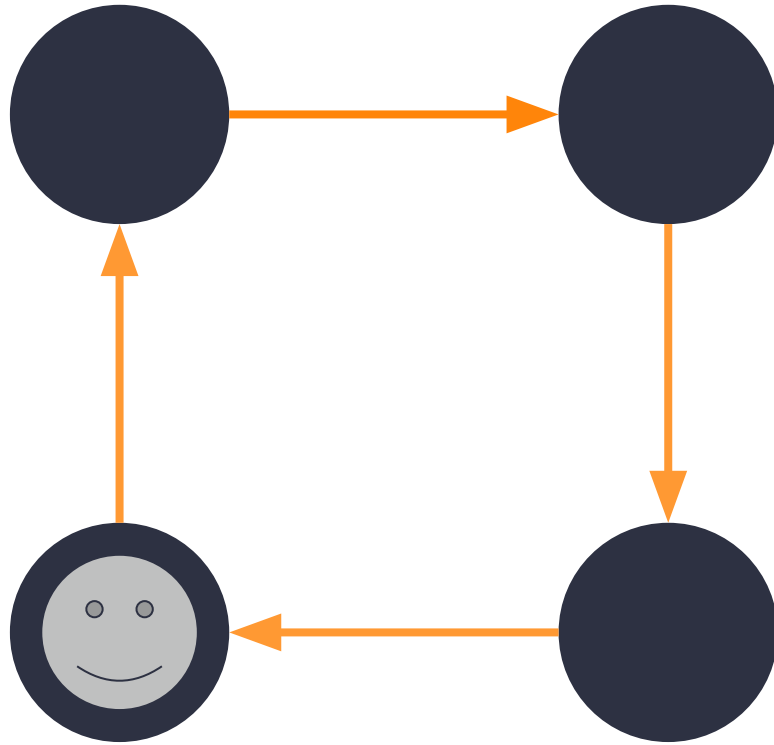
t = 1



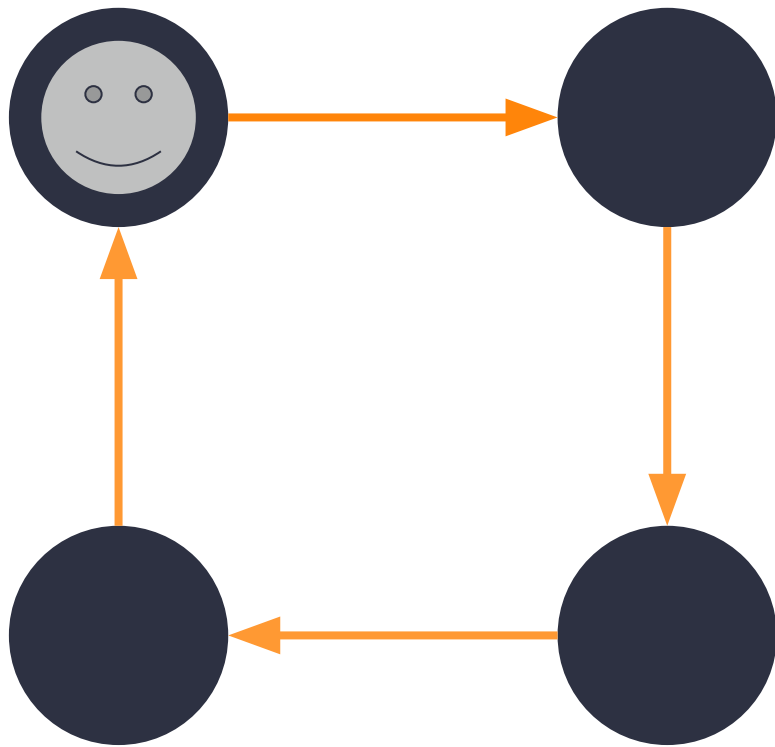
t=2



t = 3



t = 4



t = 5

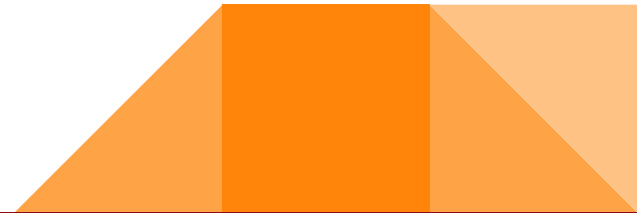
Definition: Dynamic Diameter

- discrete-time (infinite or finite)
- defined at each timestep
 - it's a sequence, not a number
- max of
 - shortest journey between all vertex pairs



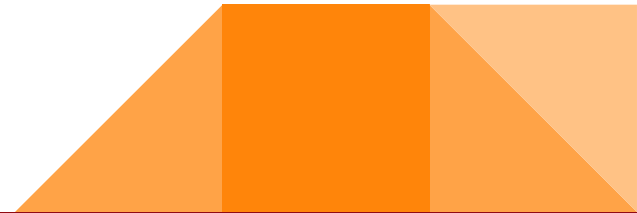
Definition: Dynamically Connected

- *Connected* if diameter is always finite
- *Uniformly connected* if bounded



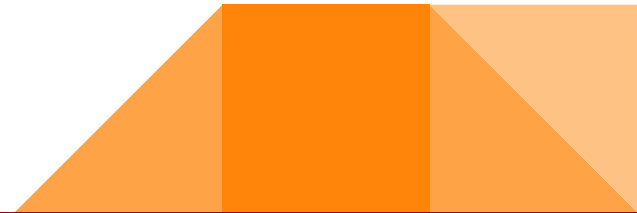
Proposition (We Didn't Mess Up I)

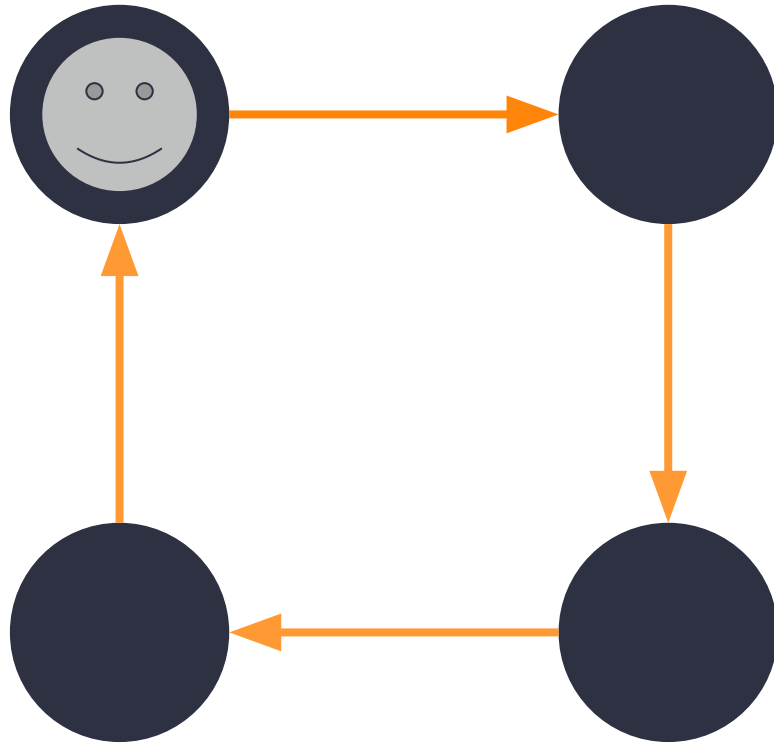
If at any time a vertex has no outbound edges, the graph is dynamically disconnected.



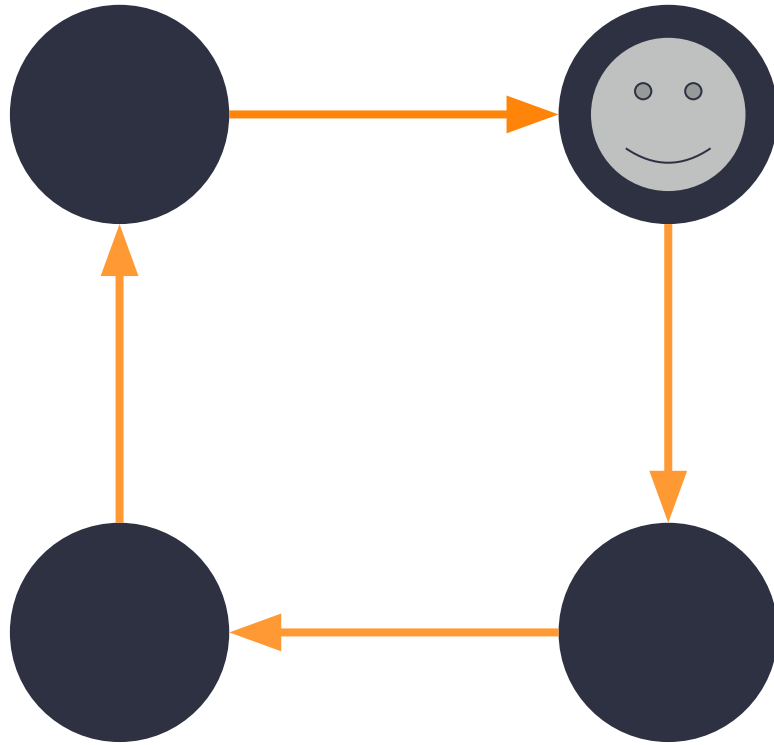
Proposition (We Didn't Mess Up II)

For a fixed dynamic sequence: diameter equals that of base graph.

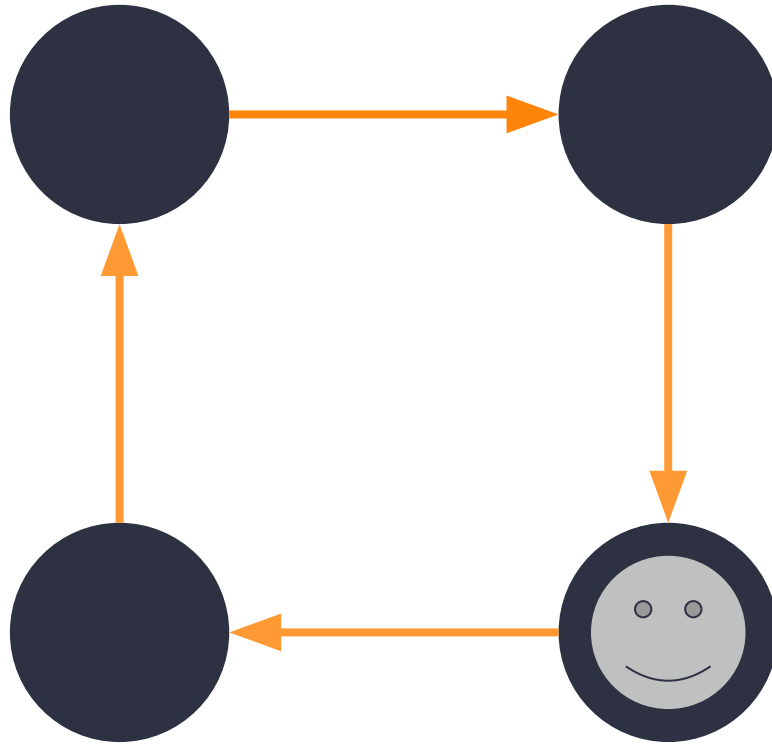




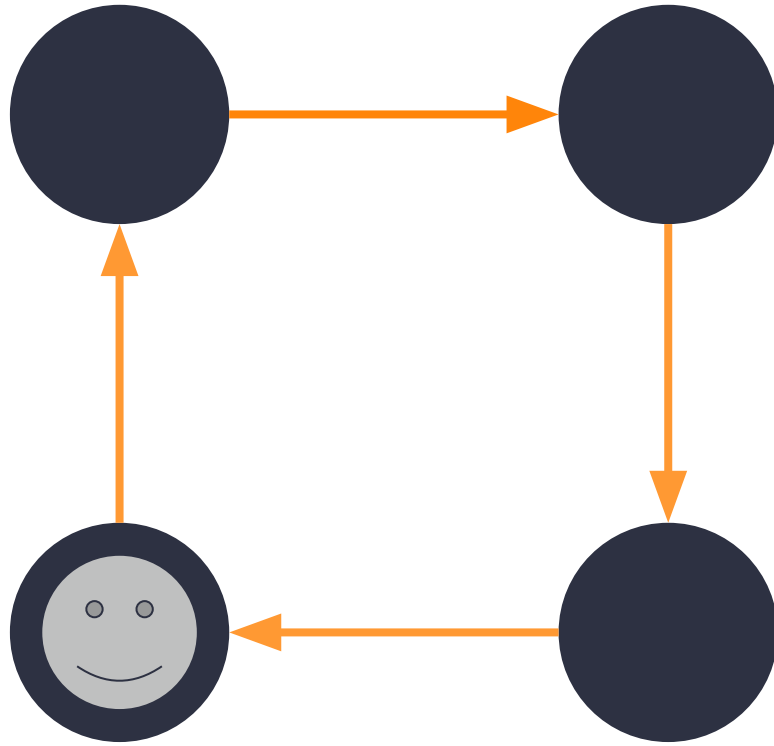
t = 1



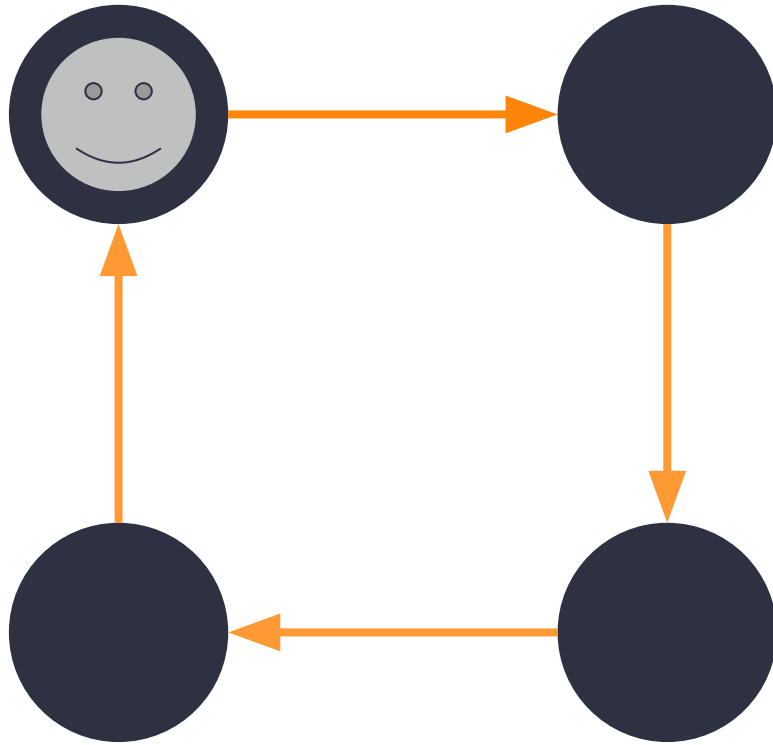
t=2



t = 3



t = 4



t = 5

Question

When does static
imply dynamic?

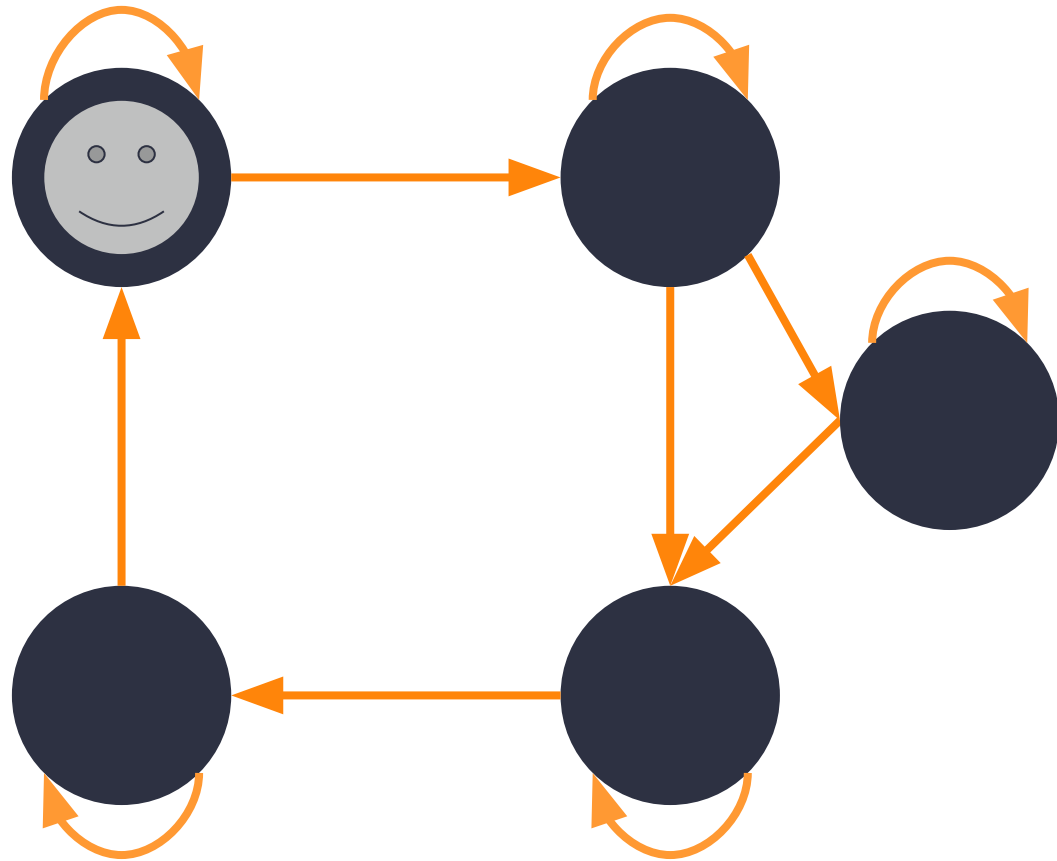
Result: Self-Loops are Sufficient

Static connectivity implies dynamic connectivity if self-loops.

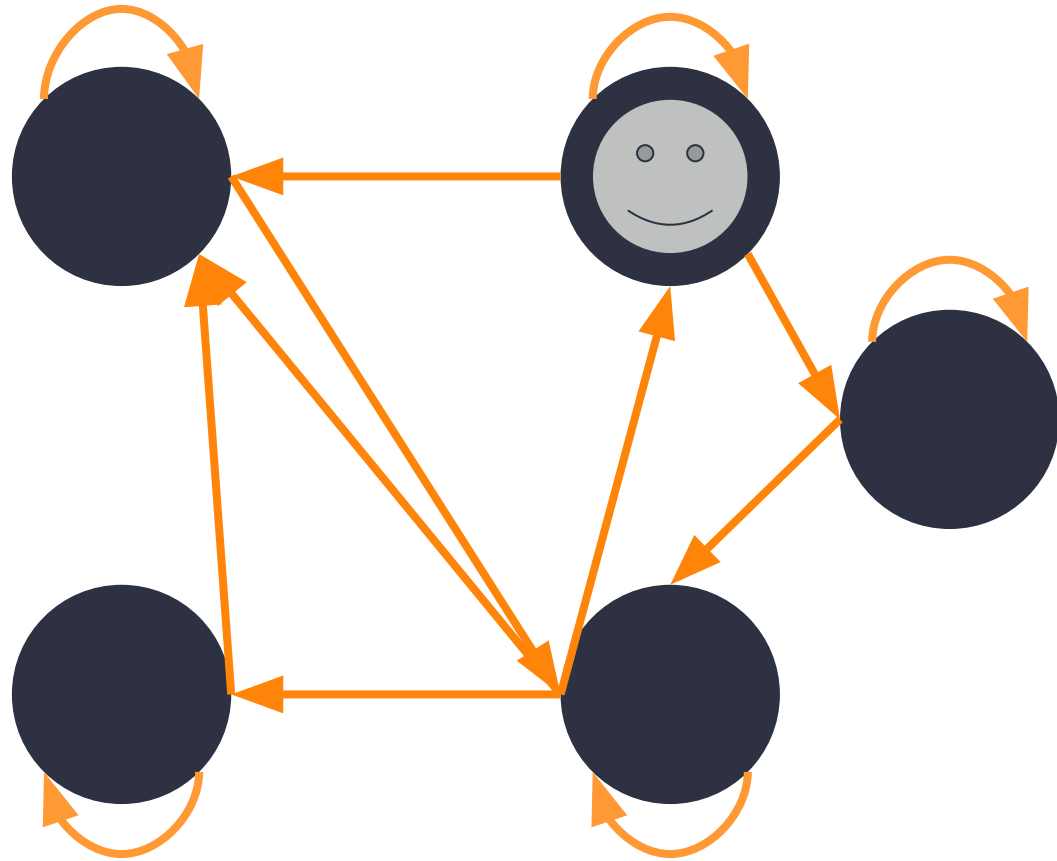
Other notes:

- Stronger (but more technical): weak monotonicity is sufficient.
- Uniform bound: number of vertices

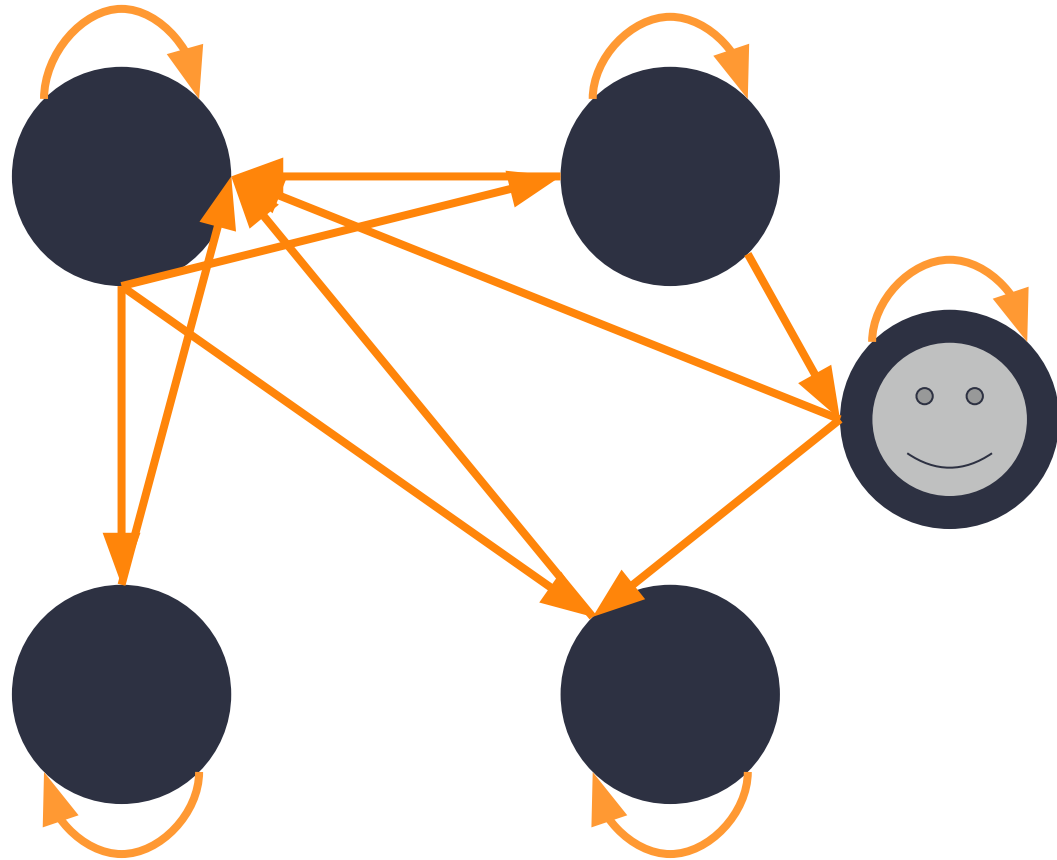




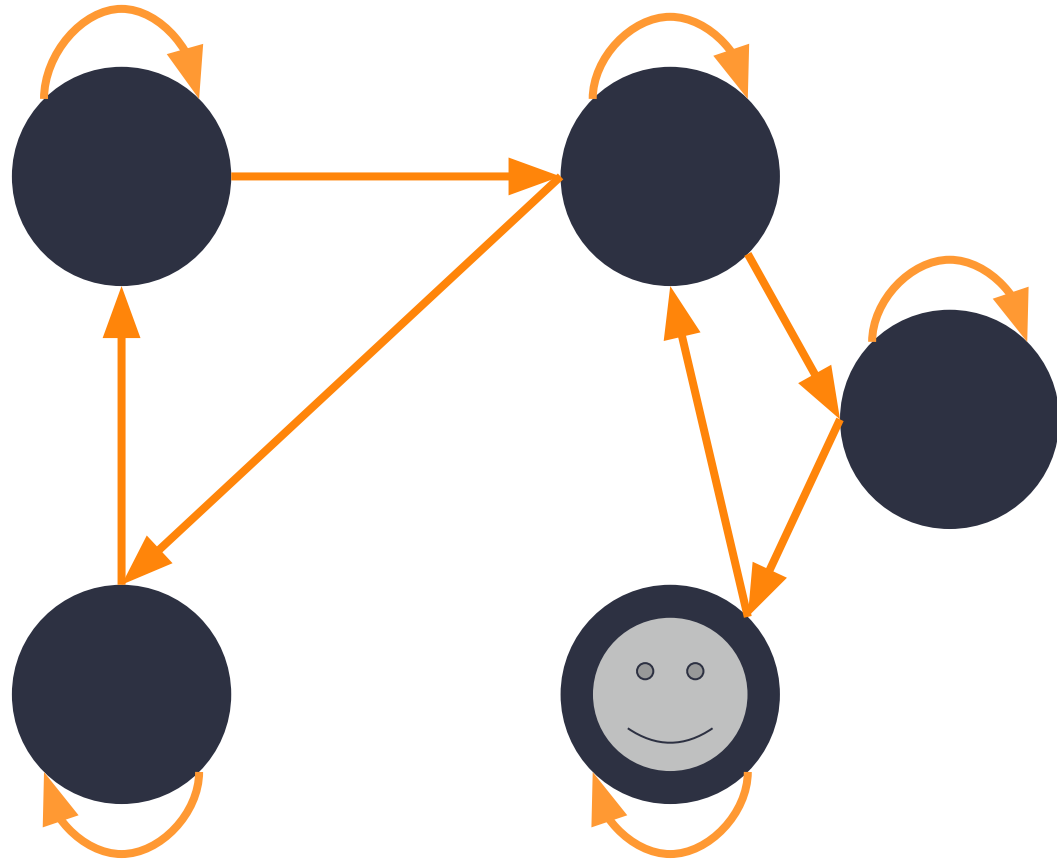
t = 1



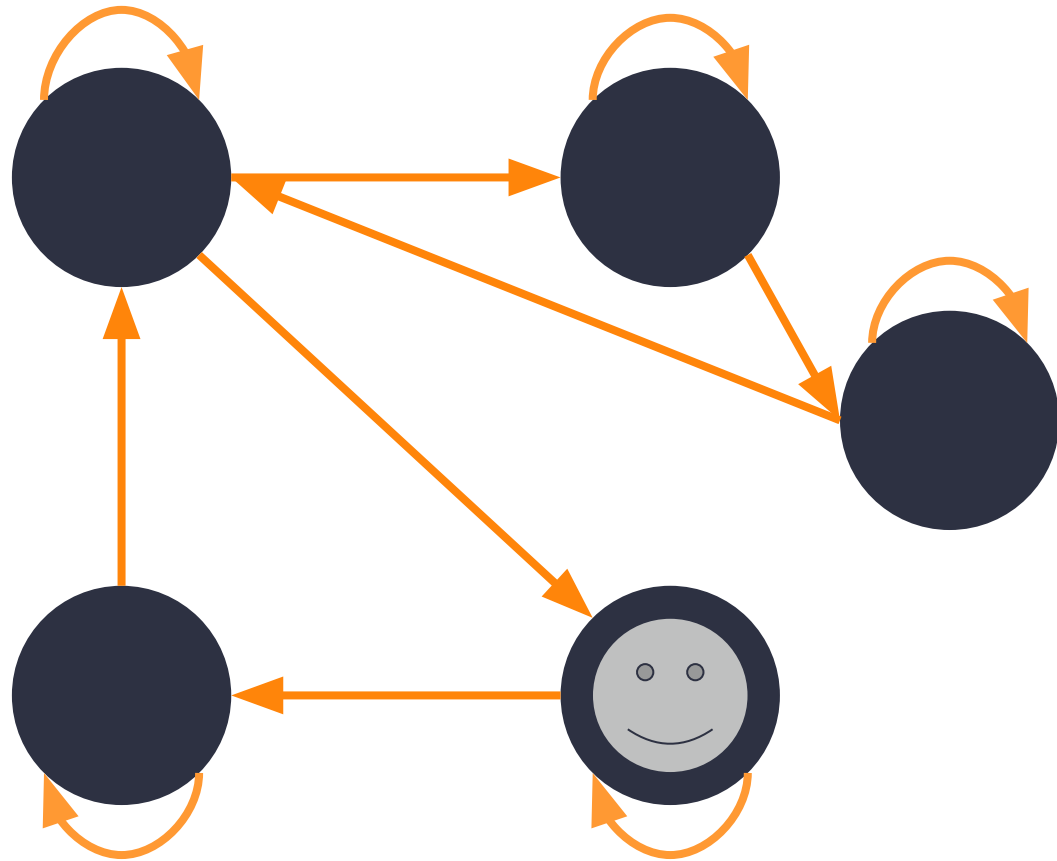
t=2



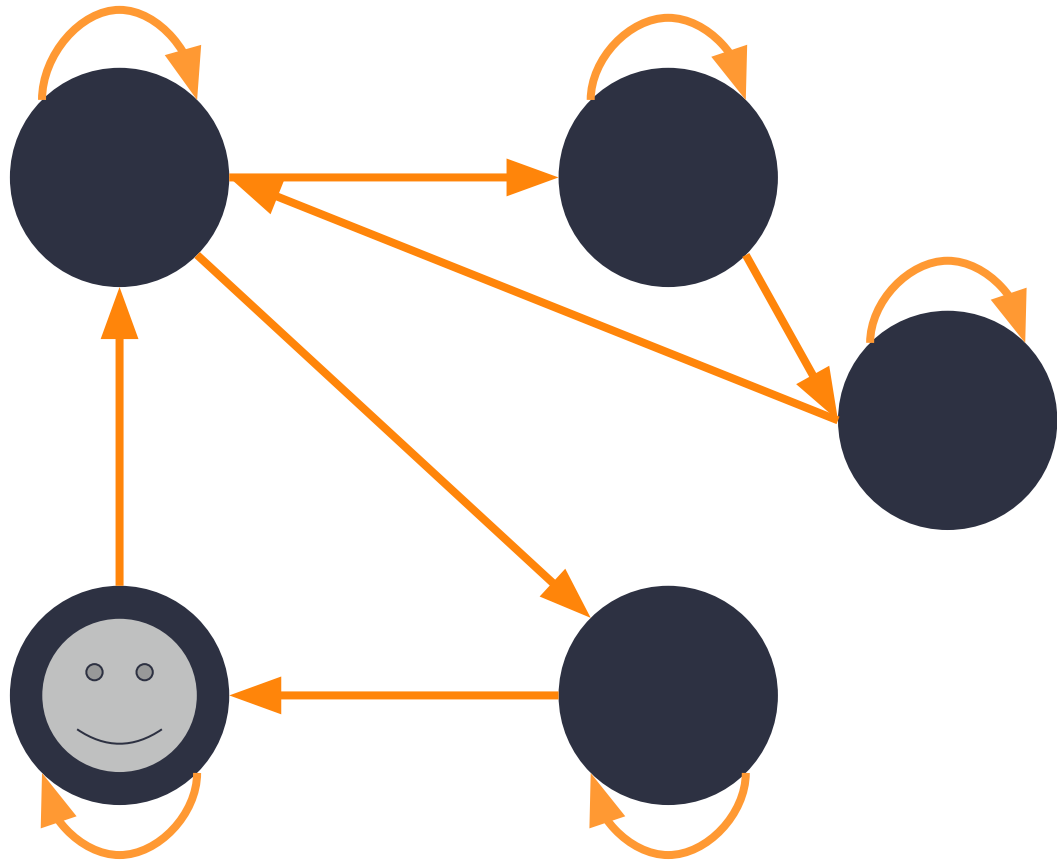
t = 3



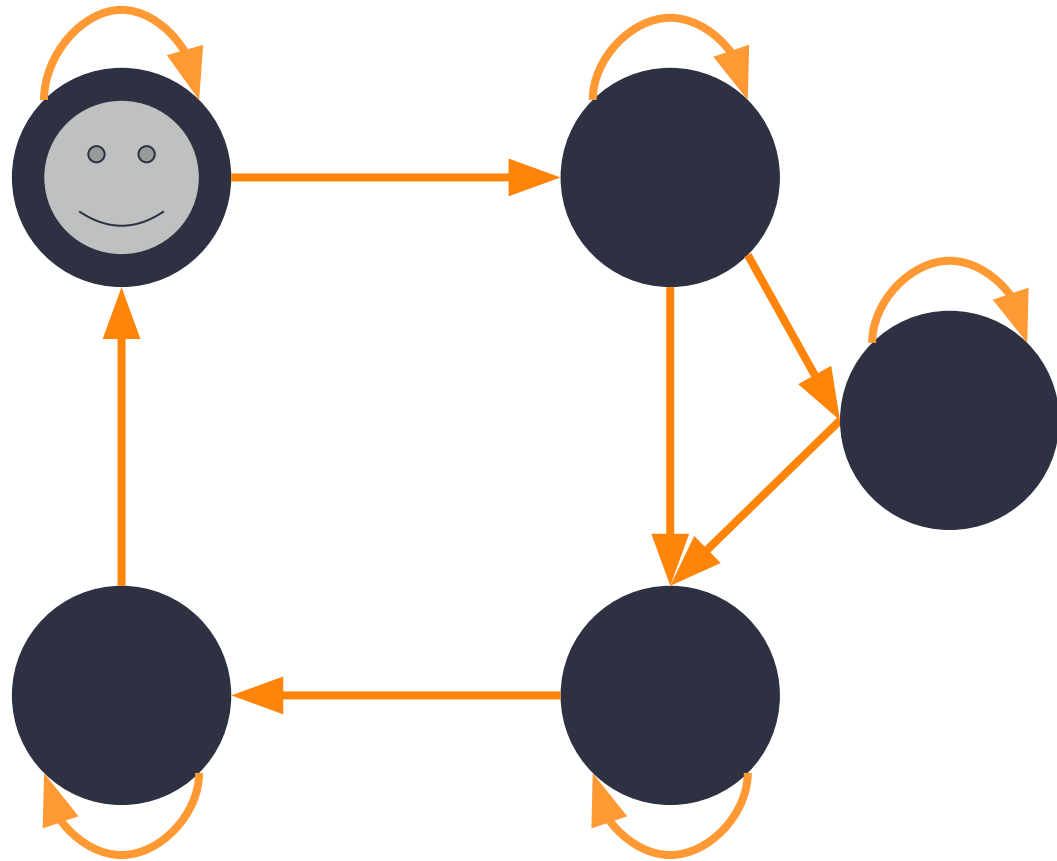
t = 4



t = 5

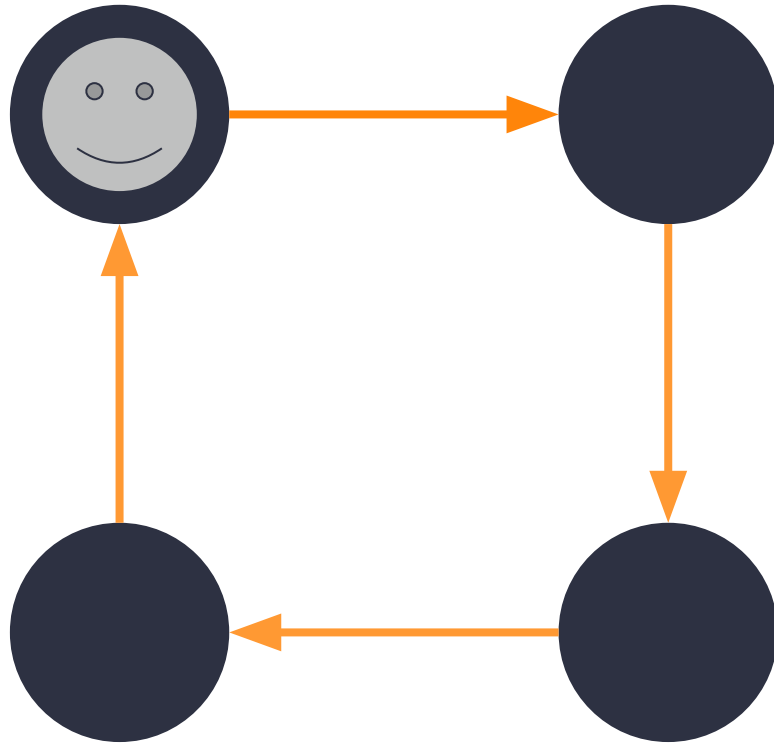


t = 6

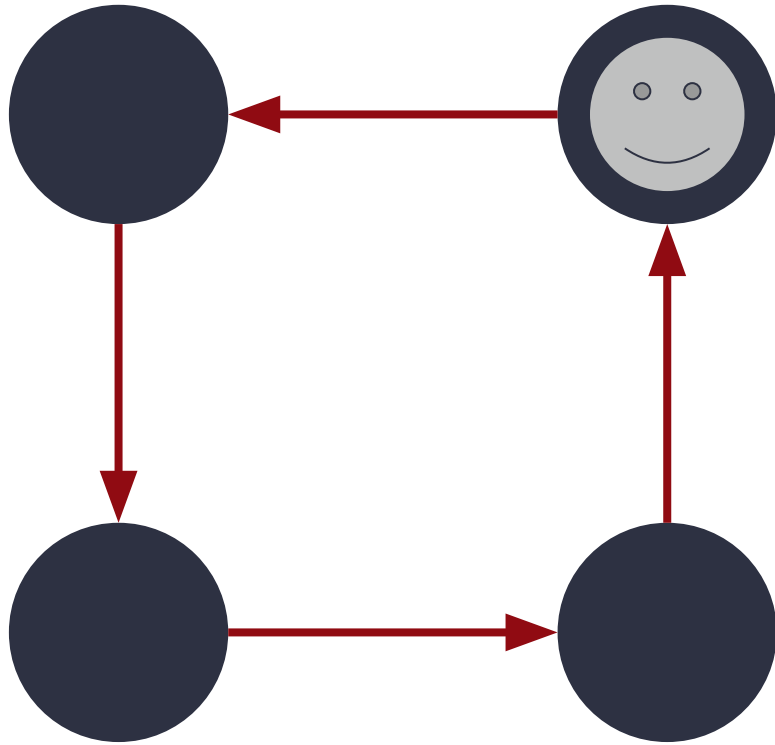


t=7

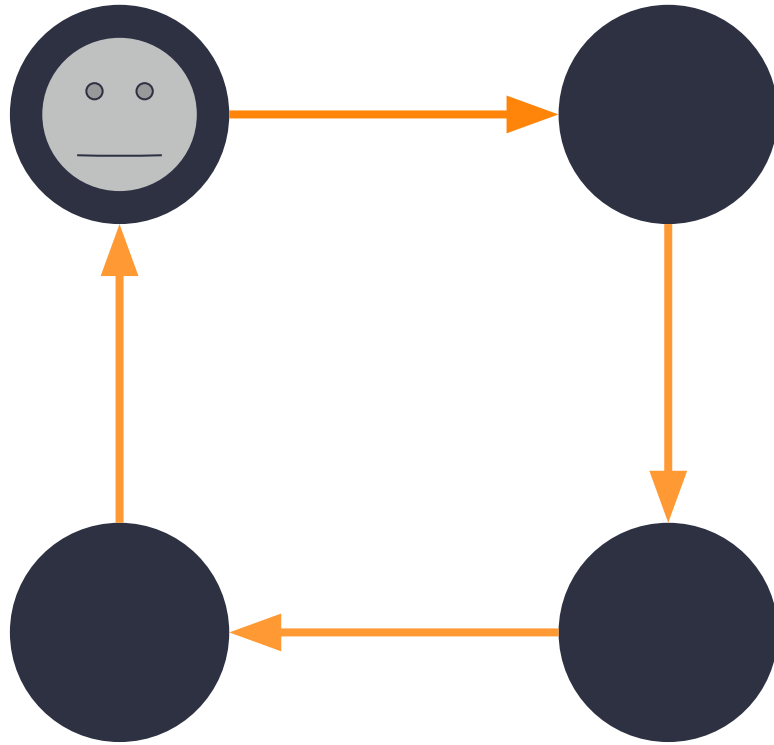
Recall



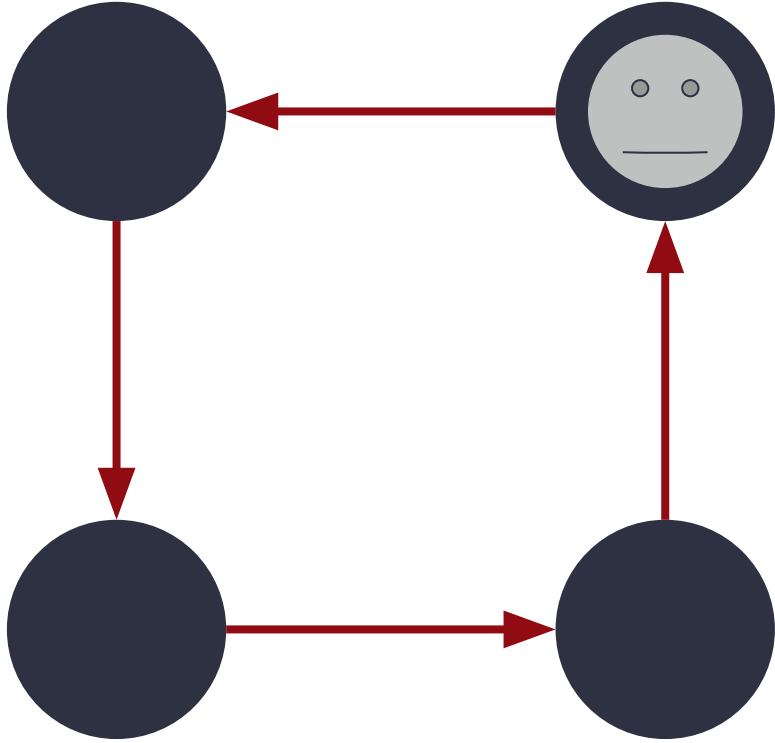
t = 1



t=2



t = 3

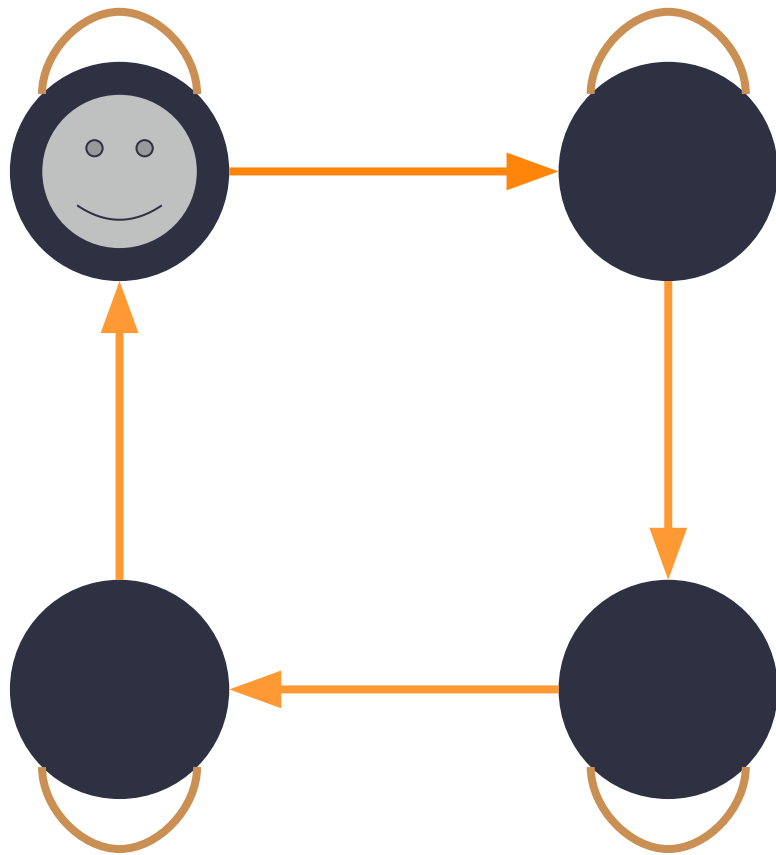


t = 4

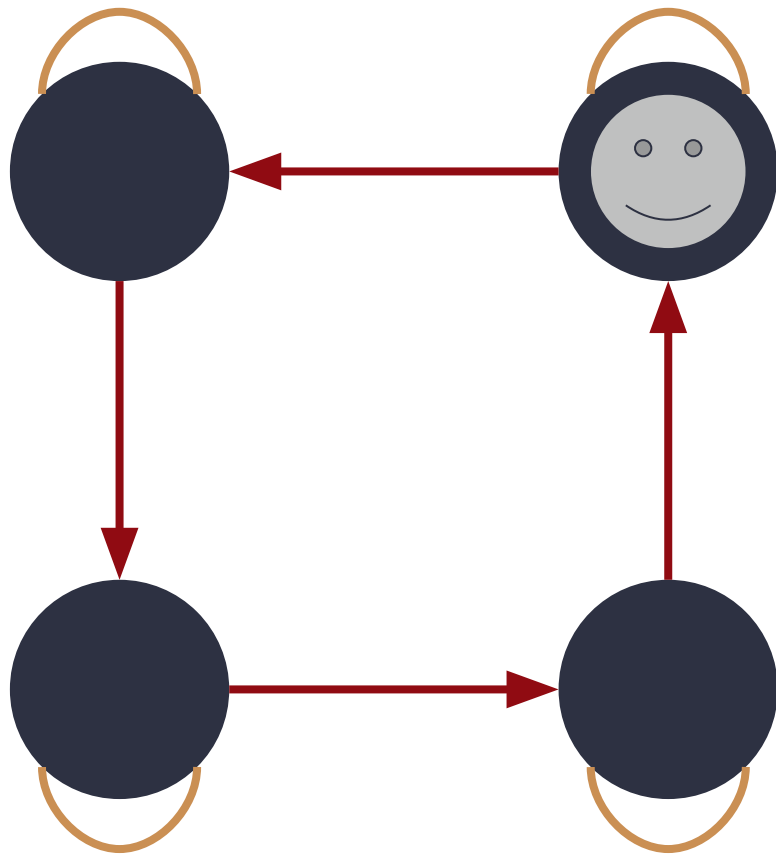


Dynamic diameter is ∞

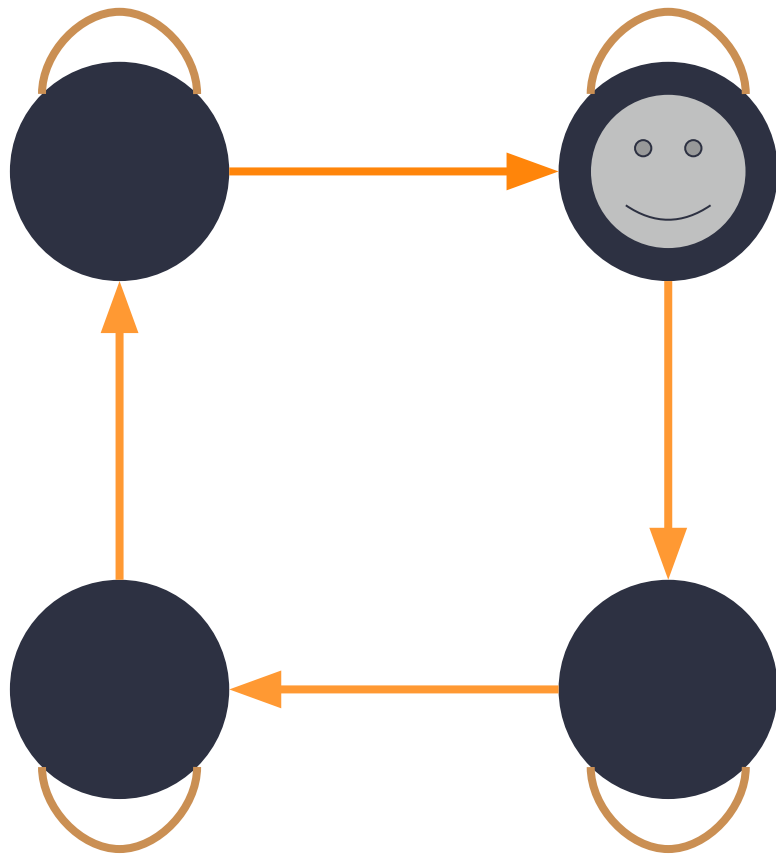
Fixed with Self-Loops



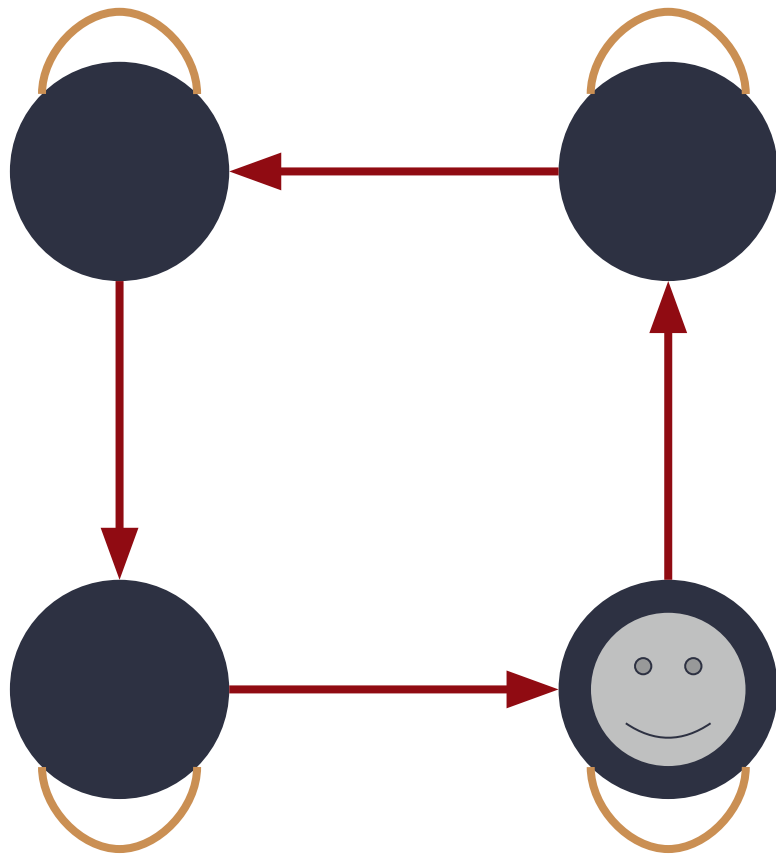
t = 1



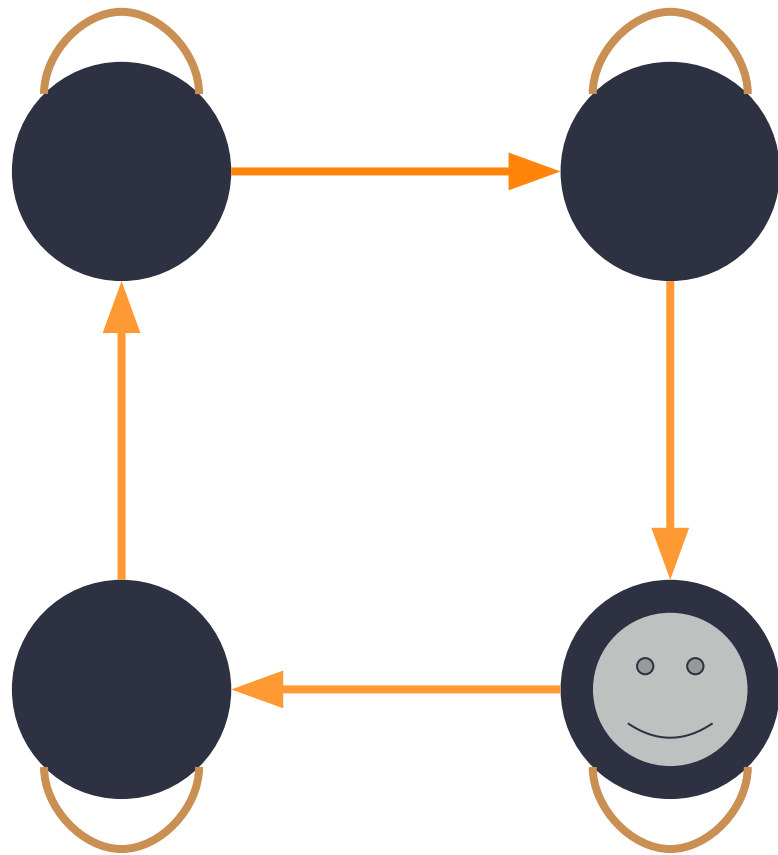
t=2



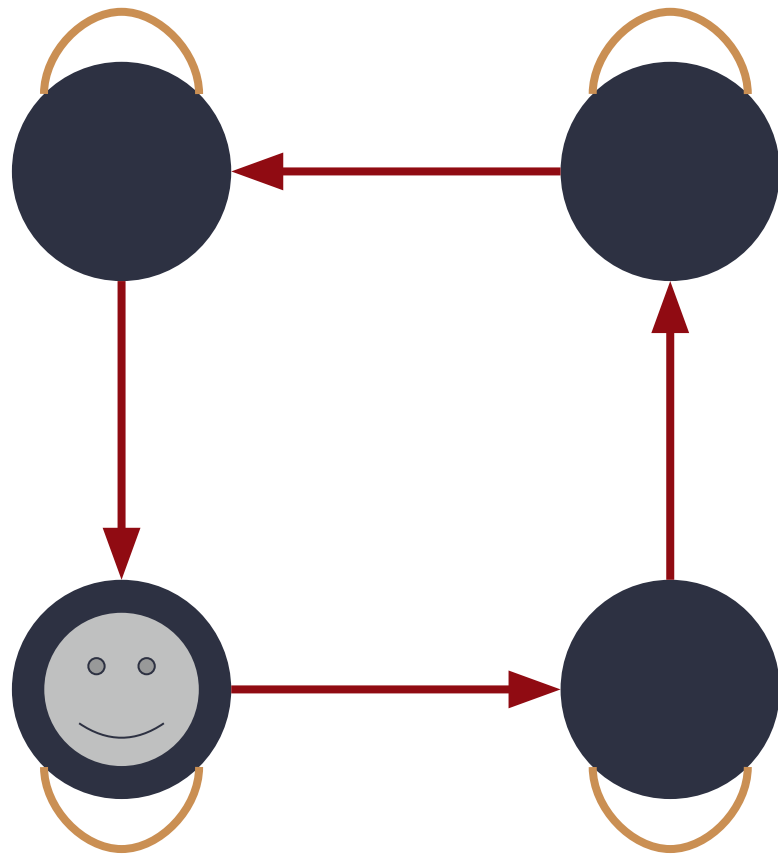
t = 3



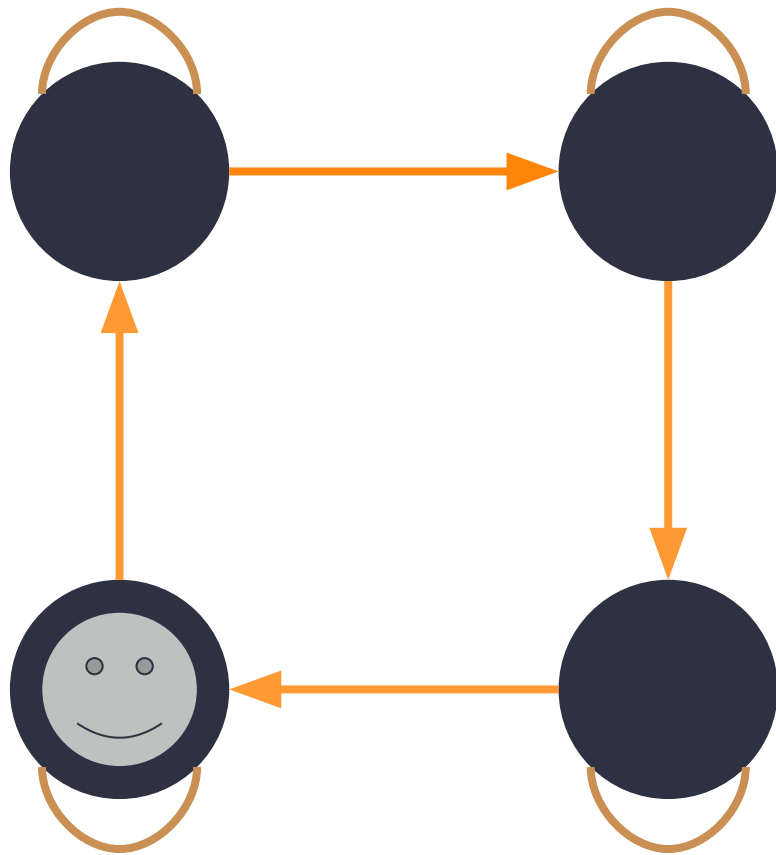
t = 4



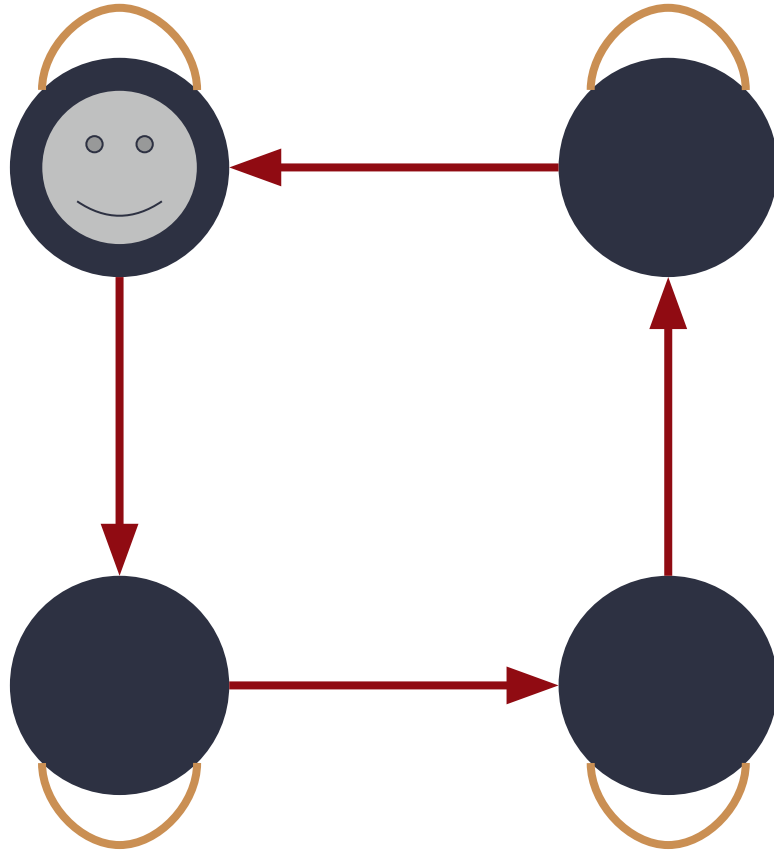
t = 5



t = 6



t = 7

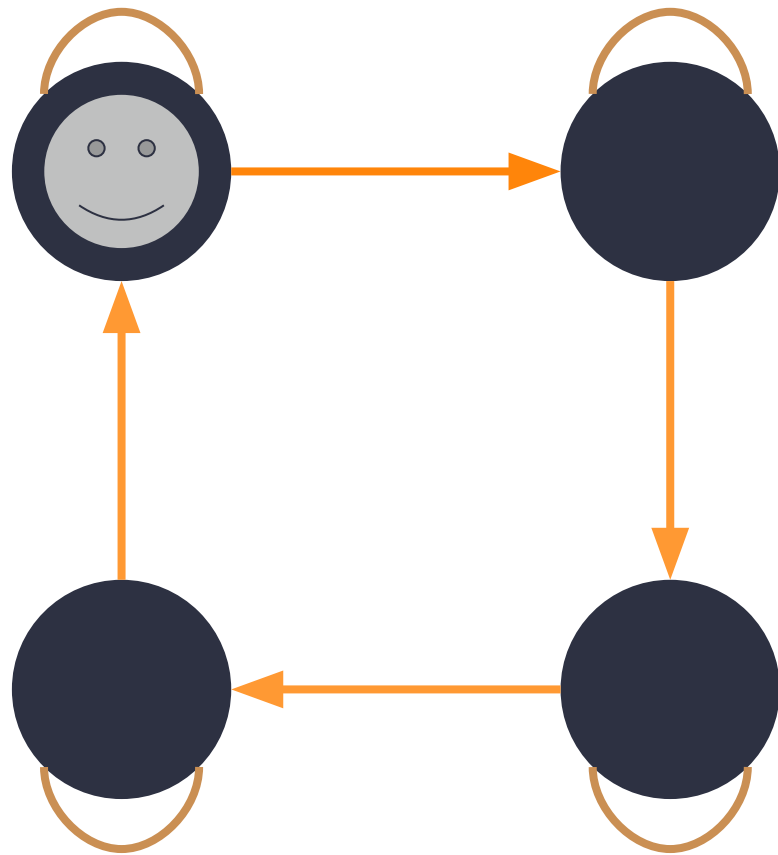


t = 8

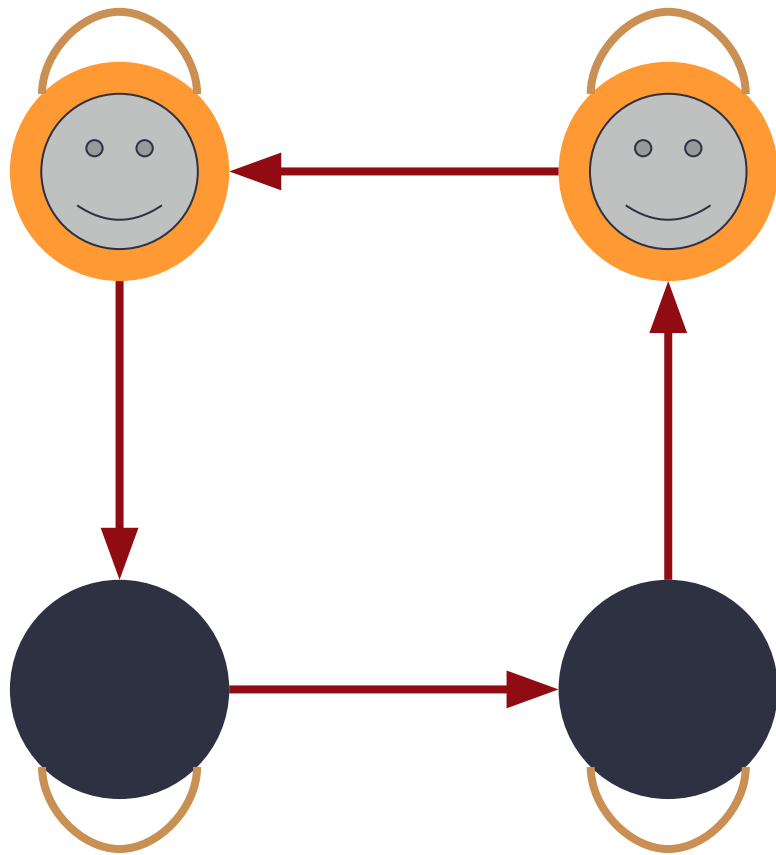


Dynamic diameter is finite

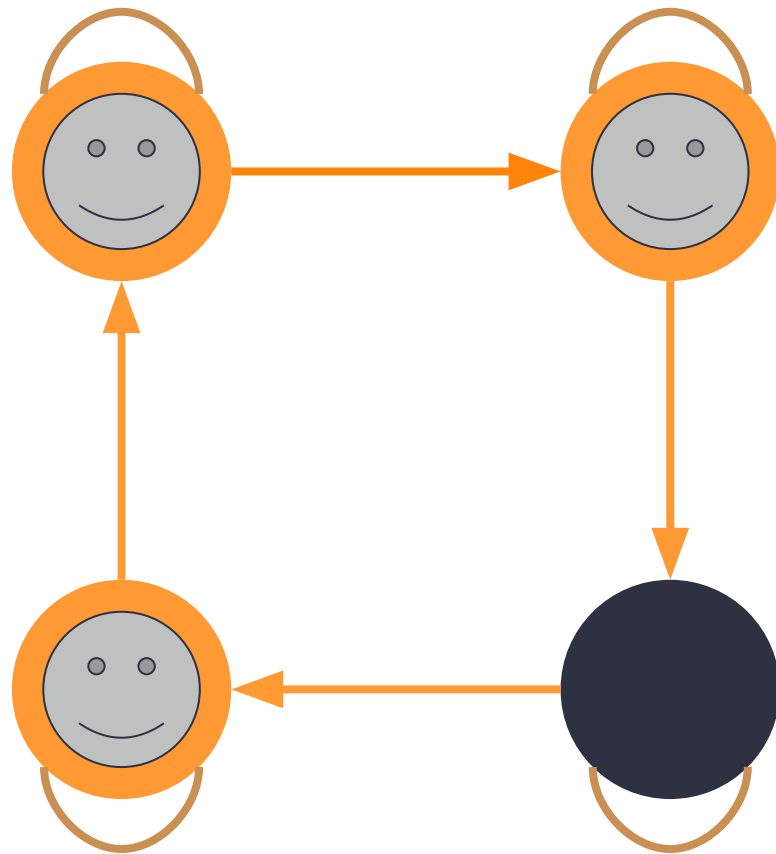
Bound Achieved



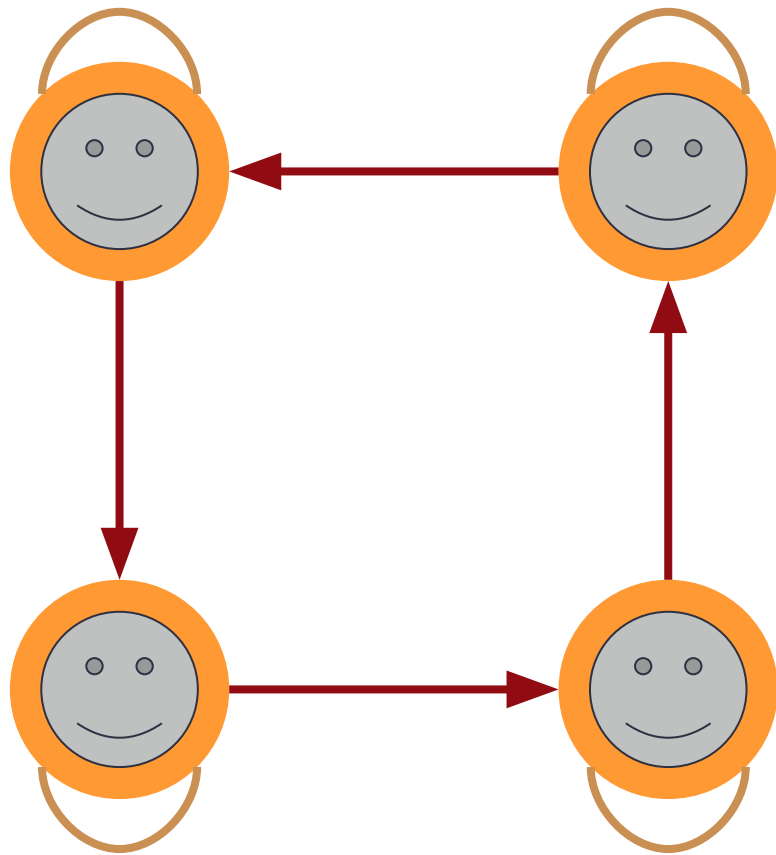
t = 1



t=2



t = 3



t = 4

Observation

Finding Conditions
is Difficult

Idea

Stochastic Case

Observation: Force Edges to Move

- A particle can get pathologically “stuck”
- Require edges to change around
 - Ensure that each possible edge appears infinitely often?



Model: Dynamic Erdős-Rényi

- Fix edge probability $p \in (0, 1)$
- At every time step for every edge, flip a (biased) coin:
 - If heads, put the edge in
 - Otherwise, leave the edge out
- Note: edges across time are i.i.d. Bernoulli



Observation

Independence
does not work

Proof: Independence \Rightarrow Disconnected

For each vertex at each timestep: probability of no outbound edges is $(1 - p)^n$, which is non-zero.



However ...

- Tweak: reflip all coins for a vertex if it has no outbound edges
 - Lose independence (a bit subtle)
- Based on simulations, conjecture: diameter is
 - constant if p constant
 - $\log n$ if p is $(\log n) / n$



Observation

Self-loops are
overpowered

Model: Dynamic Erdős-Rényi with Self-Loops

- Put in all self-loops
- Generate other edges (u, v) where $u \neq v$
 - Fix edge probability $p_{u,v} \in (0, 1)$
 - At every time step, flip a (biased) coin:
 - if heads, put in edge
 - otherwise, no edge



Proposition: Almost Surely Connected

1. Observation: every edge occurs infinitely often
2. By weak monotonicity, almost surely connected
3. Once connected, can never disconnect
4. Based on simulations, conjecture: diameter is
 - a. constant if p constant
 - b. $\log n$ if p is $(\log n) / n$



Remaining Work

1. More rigorous treatment of non-self-loop case
2. Proof of proposed bounds
3. Additional models






Applications Abound



Dynamic Graph Projects

1. Viral spread across connected populations
 - a. Rumors
 - b. COVID-19
 2. Basketball
 - a. Using TDA
 - b. Using ML**
 3. Space!
 - a. Contact graph routing**
 - b. Tropical geometry
 4. Others: animal clustering, transit, embryos, opinion dynamics
- 



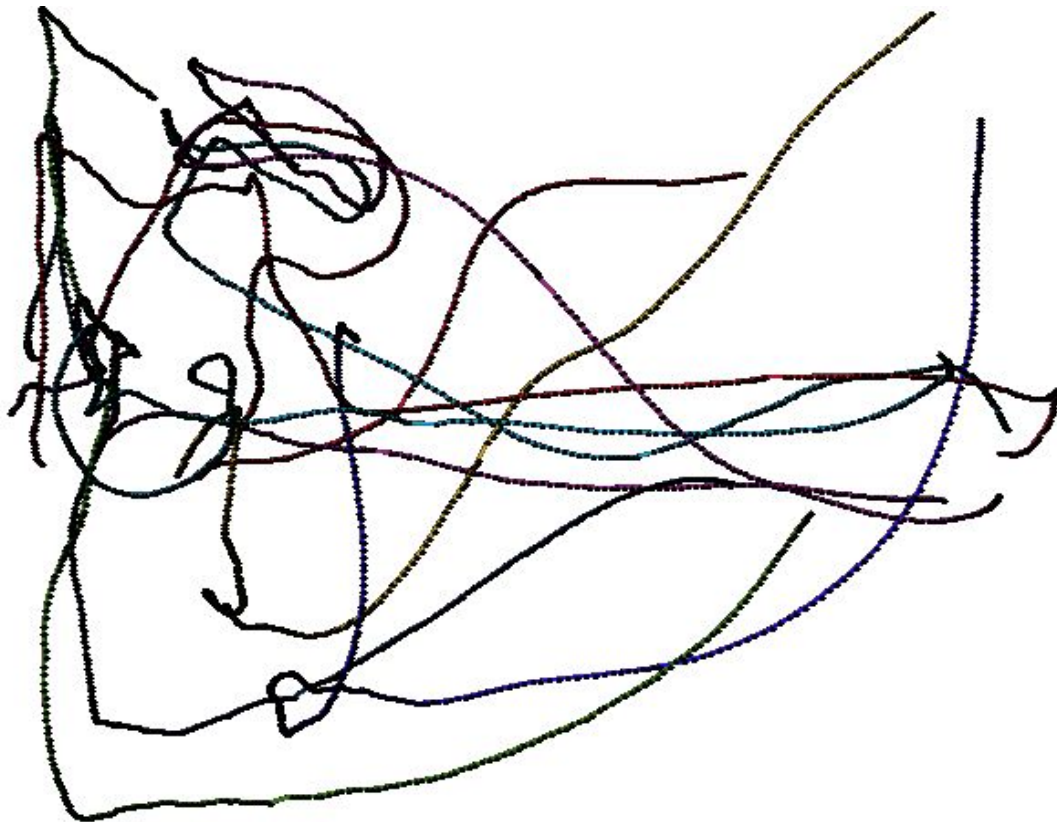
Machine Learning





Duke v. UNC (booooo!)

Multi-agent system (invasion sport)



Raw Trajectory Data

Dataset

- (x, y)-coordinates of offense, defense, basketball
- 25 frames per second (40ms per frame)



Model Goals

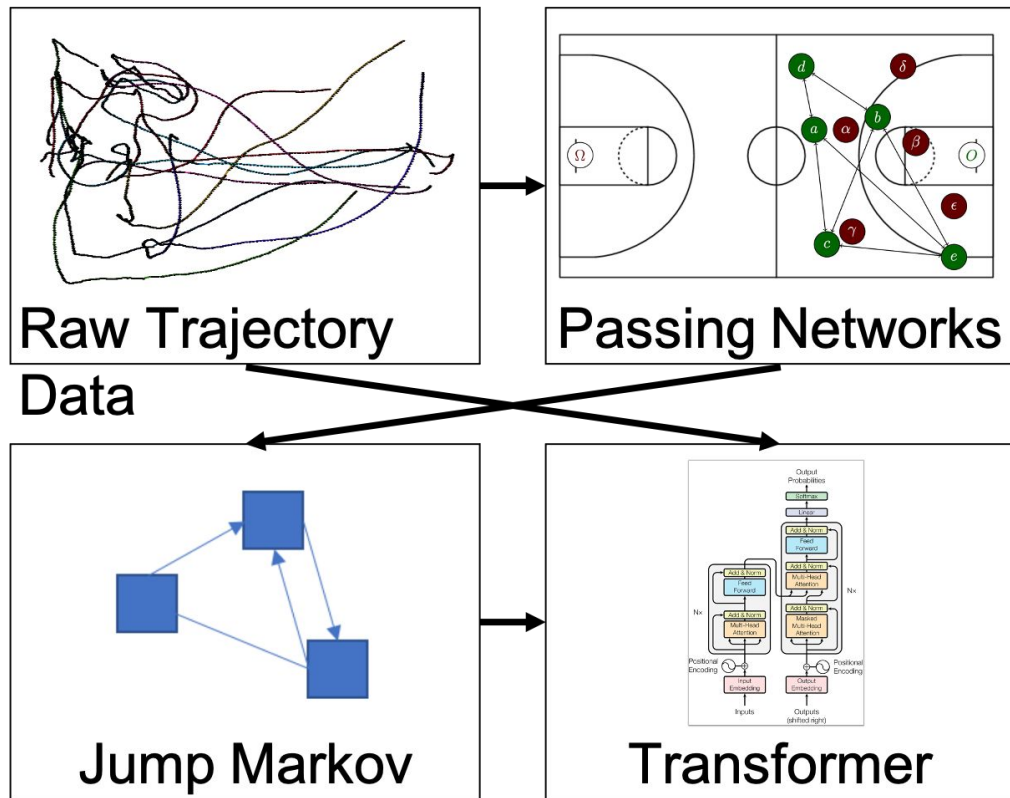
1. **Formation discovery:** a semantic understanding of the functional roles of players
2. **Compression and dimension reduction:** an efficient representation of a game, as player trajectory data is large and difficult to interpret
3. **Predictive power:** a mechanism for predicting trajectories of players
4. **Synthetic generation:** a tool for creating synthetic, but “realistic,” data



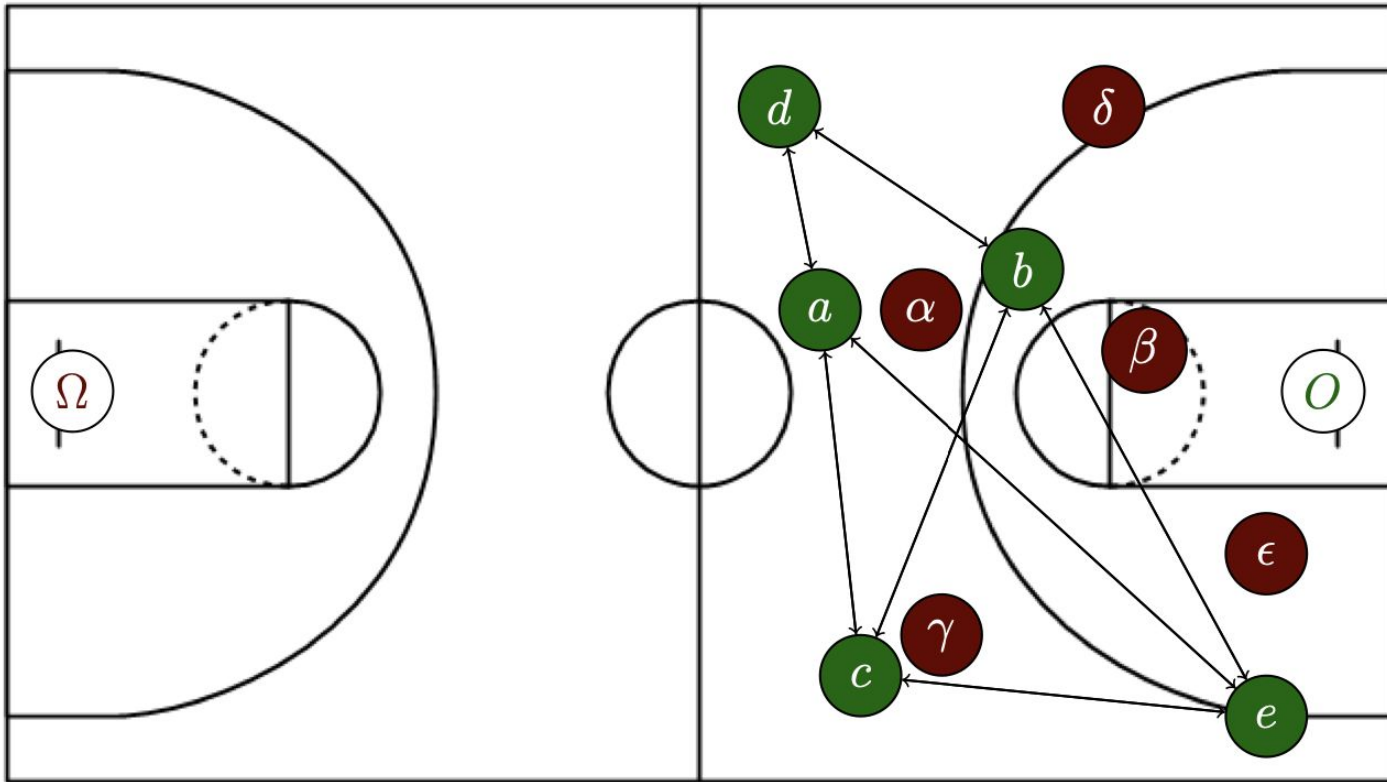
Prior Work

1. **Trajectory Prediction:** related to predictive power and synthetic generation
2. **Role Discovery:** related to formation discovery
3. **Network Analysis:** related to high compression and dimension reduction





Model Pipeline



Step 1: Dynamic Passing Network

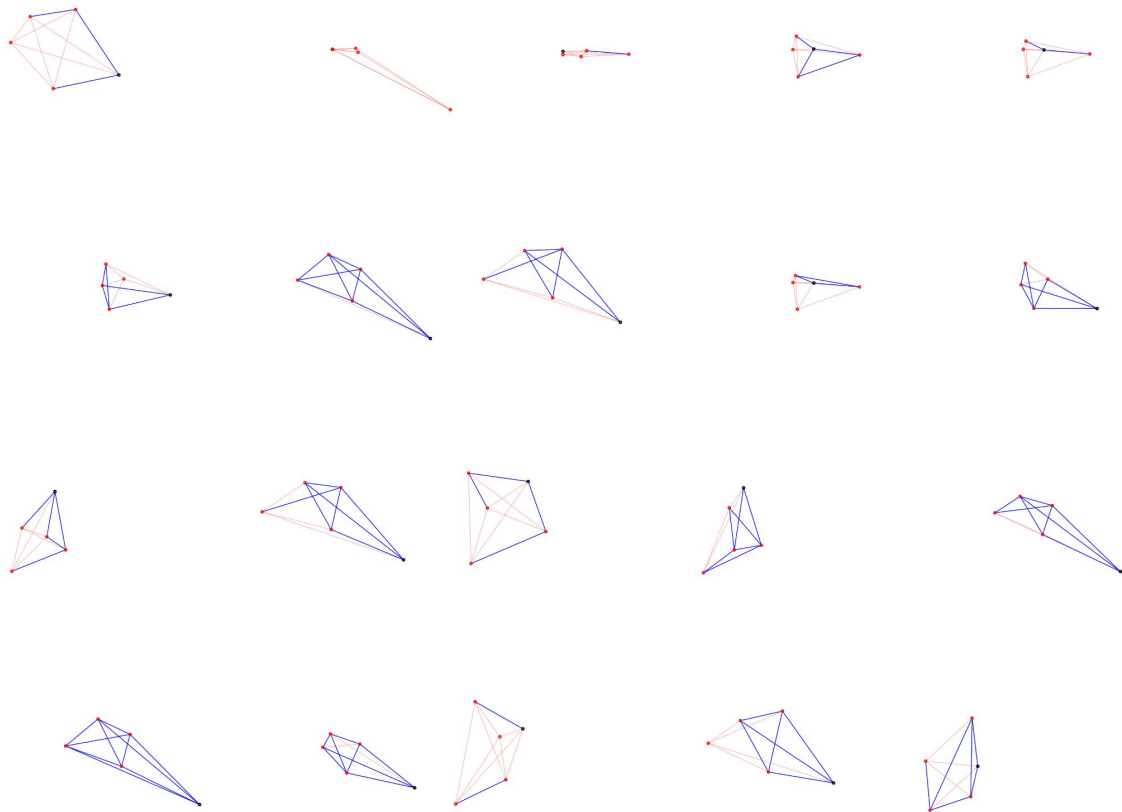
Observation

218 Graphs to
Isomorphism

Step 2: Networks to Labels

1. Compute library of graphs seen in data
2. Assign each a unique label (frequency-based?)
3. Convert networks to labels





Passing Graphy Library

Interlude: Jump Markov

$$X(t) = E_{N(t)}$$



Interlude: Jump Markov

$$\boxed{X(t)} = E_N(t)$$

continuous-time *jump*
Markov process



Interlude: Jump Markov

$$X(t) = E[N(t)]$$

Poisson counting process



Interlude: Jump Markov

discrete-time *Markov*
chain

$$X(t) = \boxed{E}_{N(t)}$$



Interlude: Jump Markov

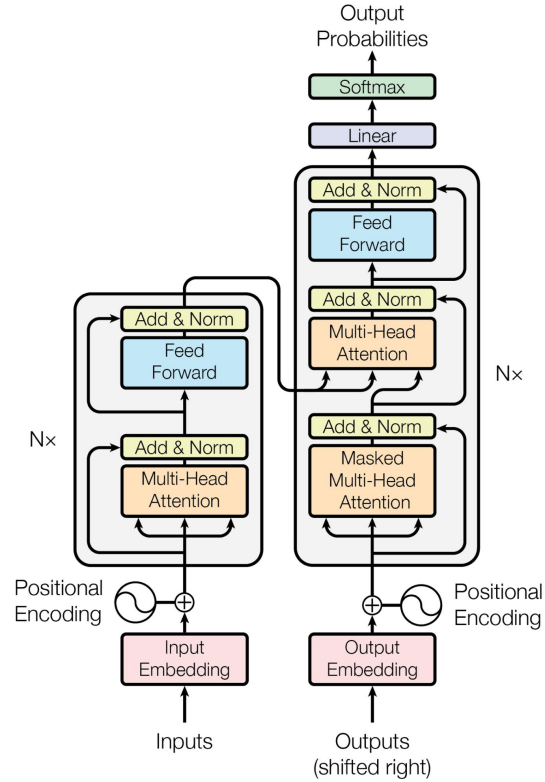
$$X(t) = E_{N(t)}$$



Idea: Semantic “Extraction”

1. Take library of passing graphs as tokens
2. Use NLP model to learn as a “language”
3. Good model: *Transformer*





Transformer Architecture

Experiment

- 40-10 prediction task
- Feed in graph data, along with base position data
- Predict trajectories
- Compare against true trajectories with MSE





66%

reduction in loss against benchmark
(40–10 trajectory prediction task)



Future Work



Theory

1. Further extensions of static properties and their relationship to their dynamic counterparts
2. Analysis of the stochastic setting
3. General framework for summarization
4. Clustering (spatiotemporal k -means)
5. Generalized optimal routing
6. Periodic systems



Applications

1. Animal herding behavior
2. General Transit Feed Specification (GTFS)
3. Twitter data
4. Additional satellite data





Acknowledgements



Q&A

